

## Solutions to text problems

### *Empirical Market Microstructure*

(2006, Oxford University Press)

### Companion *Mathematica* notebook

Joel Hasbrouck

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#### ■ Exercise 4.1 (Source notebook: RollBasicAndGeneralized)

Here is a function to build a table of all possible  $n$  successive realizations of  $q_i$ .

```
qTable[n_] := Table[(-1)^IntegerDigits[i, 2, n], {i, 0, 2^n - 1}];
```

... and for the 3-period problem, the realizations are:

```
q = qTable[3];  
TableForm[q, TableHeadings → {Automatic, {"q0", "q1", "q2"}},  
TableAlignments → Right]
```

	$q_0$	$q_1$	$q_2$
1	1	1	1
2	1	1	-1
3	1	-1	1
4	1	-1	-1
5	-1	1	1
6	-1	1	-1
7	-1	-1	1
8	-1	-1	-1

The transition probabilities for each path are:

```
PrTrans[q_] := Table[If[q[[i, j]] == q[[i, j - 1]],  $\alpha$ ,  $1 - \alpha$ ],
  {i, Length[q]}, {j, 2, Dimensions[q][[2]]}];
qp = PrTrans[q];
TableForm[qp, TableHeadings -> {Automatic, {"Pr0→1", "Pr1→2"}}],
  TableAlignments -> Right]
```

	Pr <sub>0→1</sub>	Pr <sub>1→2</sub>
1	$\alpha$	$\alpha$
2	$\alpha$	$1 - \alpha$
3	$1 - \alpha$	$1 - \alpha$
4	$1 - \alpha$	$\alpha$
5	$1 - \alpha$	$\alpha$
6	$1 - \alpha$	$1 - \alpha$
7	$\alpha$	$1 - \alpha$
8	$\alpha$	$\alpha$

The total probabilities of each path are:

```
TotalProbs = Apply[Times, qp, {1}] / 2;
TableForm[TotalProbs,
  TableHeadings -> {Automatic, {"PrTotal"}}], TableAlignments -> Right]
```

1	$\frac{\alpha^2}{2}$
2	$\frac{1}{2} (1 - \alpha) \alpha$
3	$\frac{1}{2} (1 - \alpha)^2$
4	$\frac{1}{2} (1 - \alpha) \alpha$
5	$\frac{1}{2} (1 - \alpha) \alpha$
6	$\frac{1}{2} (1 - \alpha)^2$
7	$\frac{1}{2} (1 - \alpha) \alpha$
8	$\frac{\alpha^2}{2}$

Verify that the probabilities sum to one:

```
Total[TotalProbs] // Simplify
```

```
1
```

Compute the  $v_t$ 's using the definition  $v_t = q_t - \phi q_{t-1}$  :

```
v = q[[All, {2, 3}]] - φ q[[All, {1, 2}]];
TableForm[v, TableHeadings → {Automatic, {"v1", "v2"}}], TableAlignments → Right]
```

	v <sub>1</sub>	v <sub>2</sub>
1	1 - φ	1 - φ
2	1 - φ	-1 - φ
3	-1 - φ	1 + φ
4	-1 - φ	-1 + φ
5	1 + φ	1 - φ
6	1 + φ	-1 - φ
7	-1 + φ	1 + φ
8	-1 + φ	-1 + φ

Verify that  $EV_1 = EV_2 = 0$ :

```
TotalProbs.v[[All]] // Simplify
```

```
{0, 0}
```

Var ( $v_t$ )  $\equiv \gamma_0$

```
γ0 = (TotalProbs.(v[[All]] ^ 2) // Simplify)
```

```
{1 + (2 - 4 α) φ + φ2, 1 + (2 - 4 α) φ + φ2}
```

Cov ( $v_t, v_{t-1}$ ) =  $EV_t v_{t-1} \equiv \gamma_1$

```
γ1 = (TotalProbs.(v[[All, 1]] v[[All, 2]]) // Simplify)
```

```
-4 α2 φ - (1 + φ)2 + 2 α (1 + φ)2
```

The  $v_t$  must be uncorrelated, so solve for the value of  $\phi$  that makes  $\gamma_1 = 0$ :

```
s = Solve[γ1 == 0, φ]
```

```
{{φ →  $\frac{1}{-1 + 2 \alpha}$ }, {φ → -1 + 2 α}}
```

There are two solutions, but only the second has  $|\phi| < 1$ . For example,

```
φ /. s /. α → .6
```

```
{5., 0.2}
```

So, take the second solution:

```
s = s[[2, 1]]
```

```
φ → -1 + 2 α
```

Verify that this results in  $\gamma_1 = 0$ :

```
TotalProbs.(v[[All, 1]] v[[All, 2]]) /. s // Simplify
```

```
0
```

The  $v_t$ 's have no skewness:

```
TotalProbs.(v[[All, 2]]3) /. s // Simplify
```

```
0
```

Verify that the higher-order serial moment is non-zero, i.e.,  $\text{Cov}(v_{t-1}, v_t^3) = \text{E}v_{t-1} v_t^3 \neq 0$

```
TotalProbs.(v[[All, 1]] * v[[All, 2]]3) /. s // Simplify
```

```
-32 (-1 +  $\alpha$ )2  $\alpha$ 2 (-1 + 2  $\alpha$ )
```

```
ClearAll[q, u, v,  $\gamma_0$ ,  $\gamma_1$ ]
```

#### ■ Exercise 4.2 (Source notebook: RollBasicAndGeneralized)

The model is:

```
mRule = m_t_ -> m_{t-1} + u_t ;
pRule = p_t_ -> m_t + c q_t ;
 $\Delta p_{\text{Rule}} = \Delta p_{t\_} -> (p_t / . p_{\text{Rule}} / . m_{\text{Rule}}) - (p_{t-1} / . p_{\text{Rule}}) ;$ 
 $\Delta p_t / . \Delta p_{\text{Rule}}$ 
```

```
-c q_{-1+t} + c q_t + u_t
```

We need some alternate rules for the expectation operator to recognize the correlation between  $q_t$  and  $q_{t-1}$ .

```
 $\mathcal{E}\text{AlternateRules} = \{$ 
 $\mathcal{E}[q_{\_}^2] \rightarrow 1, \mathcal{E}[u_{\_}^2] \rightarrow \sigma_u^2,$ 
 $\mathcal{E}[q_{\_} u_{\_}] \rightarrow 0, \mathcal{E}[q_{t\_} q_{s\_}] \rightarrow 0 / ; \text{Abs}[t - s] > 1,$ 
 $\mathcal{E}[q_{t\_} q_{s\_}] \rightarrow \rho / ; \text{Abs}[t - s] == 1,$ 
 $\mathcal{E}[u_{t\_} u_{s\_}] \rightarrow 0 / ; t \neq s \} ;$ 
```

```
 $\mathcal{E}\text{Rules} = \text{Join}[\mathcal{E}\text{AlternateRules}, \mathcal{E}\text{LinearityRules}] ;$ 
```

To get the variance, we multiply everything out, and take the expectation:

```
 $\mathcal{E}[\text{Expand}[\Delta p_t^2 / . \Delta p_{\text{Rule}}]]$ 
```

```
 $\mathcal{E}[c^2 q_{-1+t}^2 - 2 c^2 q_{-1+t} q_t + c^2 q_t^2 - 2 c q_{-1+t} u_t + 2 c q_t u_t + u_t^2]$ 
```

Using the rules described above to eliminate terms that have zero expectation:

```
% //.  $\mathcal{E}_{\text{Rules}}$  // Simplify
```

$$-2 c^2 (-1 + \rho) + \sigma_u^2$$

Cov ( $\Delta p_t$ ,  $\Delta p_{t-1}$ ):

```
 $\mathcal{E}$ [Expand[ $\Delta p_t \Delta p_{t-1}$  /.  $\Delta p_{\text{Rule}}$ ]]
```

$$\mathcal{E} [c^2 q_{-2+t} q_{-1+t} - c^2 q_{-1+t}^2 - c^2 q_{-2+t} q_t + c^2 q_{-1+t} q_t - c q_{-1+t} u_{-1+t} + c q_t u_{-1+t} - c q_{-2+t} u_t + c q_{-1+t} u_t + u_{-1+t} u_t]$$

```
 $\mathcal{E}$ [Expand[ $\Delta p_t \Delta p_{t-1}$  /.  $\Delta p_{\text{Rule}}$ ]] //.  $\mathcal{E}_{\text{Rules}}$  // FullSimplify
```

$$c^2 (-1 + 2 \rho)$$

```
 $\mathcal{E}$ [Expand[ $\Delta p_t \Delta p_{t-2}$  /.  $\Delta p_{\text{Rule}}$ ]] //.  $\mathcal{E}_{\text{Rules}}$  // Simplify
```

$$-c^2 \rho$$

```
 $\mathcal{E}$ [Expand[ $\Delta p_t \Delta p_{t-3}$  /.  $\Delta p_{\text{Rule}}$ ]] //.  $\mathcal{E}_{\text{Rules}}$  // Simplify
```

$$0$$

Verify that  $\sqrt{-\text{Cov}(\Delta p_t, \Delta p_{t-1})} < c$ :

```
Simplify[ $\sqrt{-\mathcal{E}[\text{Expand}[\Delta p_t \Delta p_{t-1} /. \Delta p_{\text{Rule}}]]} < c$ ,  
Assumptions  $\rightarrow \{0 < \rho < 1/2, c > 0\}$ ]
```

True

#### ■ Exercise 4.3 (Source notebook: RollBasicAndGeneralized)

Model:

```
 $m_{\text{Rule}} = m_t \rightarrow m_{t-1} + u_t$ ;  
 $p_{\text{Rule}} = p_t \rightarrow m_t + c q_t$ ;  
 $\Delta p_{\text{Rule}} = \Delta p_t \rightarrow (p_t /. p_{\text{Rule}} /. m_{\text{Rule}}) - (p_{t-1} /. p_{\text{Rule}})$ ;  
 $\Delta p_t /. \Delta p_{\text{Rule}}$ 
```

$$-c q_{-1+t} + c q_t + u_t$$

Modified expectations rules:

```

 $\mathcal{E}\text{AlternateRules} = \{$ 
 $\mathcal{E}[q_-^2] \rightarrow 1,$ 
 $\mathcal{E}[u_-^2] \rightarrow \sigma_u^2,$ 
 $\mathcal{E}[q_s u_t] \rightarrow \rho \sigma_u ; t = s,$ 
 $\mathcal{E}[q_s u_t] \rightarrow 0 ; t \neq s,$ 
 $\mathcal{E}[q_t q_s] \rightarrow 0 ; t \neq s,$ 
 $\mathcal{E}[u_t u_s] \rightarrow 0 ; t \neq s\};$ 

```

```

 $\mathcal{E}\text{Rules} = \text{Join}[\mathcal{E}\text{AlternateRules}, \mathcal{E}\text{LinearityRules}];$ 

```

```

 $\mathcal{E}[\text{Expand}[\Delta p_t^2 /. \Delta p_{\text{Rule}}]] // . \mathcal{E}\text{Rules} // \text{FullSimplify}$ 

```

```

 $2 c^2 + \sigma_u^2 + 2 c \rho \sigma_u$ 

```

```

 $\mathcal{E}[\text{Expand}[\Delta p_t \Delta p_{t-1} /. \Delta p_{\text{Rule}}]] // . \mathcal{E}\text{Rules} // \text{Simplify}$ 

```

```

 $-c (c + \rho \sigma_u)$ 

```

```

 $\mathcal{E}[\text{Expand}[\Delta p_t \Delta p_{t-2} /. \Delta p_{\text{Rule}}]] // . \mathcal{E}\text{Rules} // \text{Simplify}$ 

```

```

 $0$ 

```

Verify that  $\sqrt{-\text{Cov}(\Delta p_t, \Delta p_{t-1})} > c$ :

```

 $\text{Simplify}[\sqrt{-\mathcal{E}[\text{Expand}[\Delta p_t \Delta p_{t-1} /. \Delta p_{\text{Rule}}]]} // . \mathcal{E}\text{Rules} > c,$ 
 $\text{Assumptions} \rightarrow \{0 < \rho, \sigma_u > 0, c > 0\}]$ 

```

```

True

```

### ■ Exercise 5.1 (Different $\mu$ s for different brokers, Source notebook: SequentialTrade)

**Ask**

$$\frac{VLo \delta (-1 + \mu) + VHi (-1 + \delta) (1 + \mu)}{-1 + (-1 + 2 \delta) \mu}$$

**Ask /.  $\delta \rightarrow 1/2$  // FullSimplify**

$$\frac{1}{2} (VHi + VLo + VHi \mu - VLo \mu)$$

```
Profitsb = (Ask /.  $\mu \rightarrow \mu_{\text{Other}}$ ) - (Ask /.  $\mu \rightarrow \mu_b$ ) /.  $\delta \rightarrow 1/2$  // FullSimplify
```

$$-\frac{1}{2} (\text{VHi} - \text{VLo}) (\mu_b - \mu_{\text{Other}})$$

```
Simplify[Profitsb > 0, {0 <  $\mu_b$  < 1, 0 <  $\mu_{\text{Other}}$  < 1,  $\mu_b$  <  $\mu_{\text{Other}}$ , VHi > VLo, 0 <  $\delta$  < 1}]
```

```
True
```

■ Exercise 5.2 (Informed trading only in low state, Source notebook: SequentialTrade)

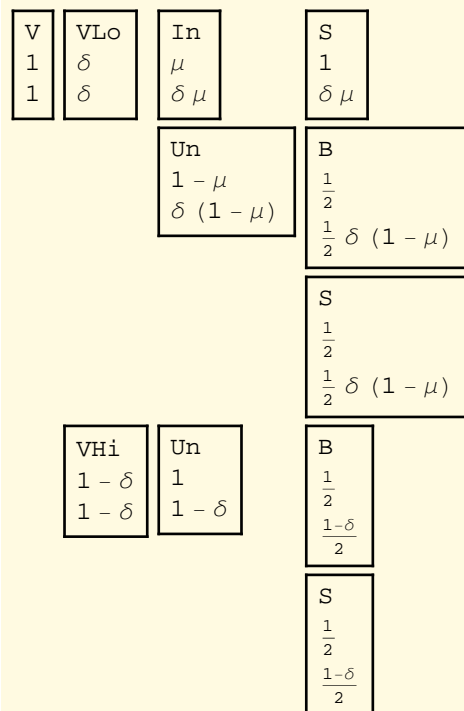
```
LabelTree = {V, {VLo, {In, S}, {Un, B, S}}, {VHi, {Un, B, S}}};
LabelTree // ShowTree
```

```
V VLo In S
    Un B
      S
    VHi Un B
          S
```

```
PrTree = LabelTree /. {VLo, {In, S}, a_} => {VLo, {In, 1}, a} /. B | S -> 1/2 /. In ->  $\mu$  /.
    {VHi, {Un, a_}} => {VHi, {1, a}} /. Un -> 1 -  $\mu$  /. VLo ->  $\delta$  /. VHi -> 1 -  $\delta$  /. V -> 1;
```

```
ExTree = BuildTree[LabelTree, PrTree];
```

```
ShowTree[ExTree]
```



Verify that terminal node total probabilities add up to one:

`Pr[ExTree, B] + Pr[ExTree, S] // Simplify`

1

Conditional on a buy, the revised  $\delta$  is:

`$\delta B = \text{Pr}[\text{ExTree}, VLo, B] / \text{Pr}[\text{ExTree}, B] // \text{Simplify}$`

$$\frac{\delta (-1 + \mu)}{-1 + \delta \mu}$$

Conditional on a sell ...

`$\delta S = \text{Pr}[\text{ExTree}, VLo, S] / \text{Pr}[\text{ExTree}, S] // \text{Simplify}$`

$$\frac{\delta (1 + \mu)}{1 + \delta \mu}$$

`$\text{Ask} = \text{Simplify}[\delta B VLo + (1 - \delta B) VHi]$`

$$\frac{VHi (-1 + \delta) + VLo \delta (-1 + \mu)}{-1 + \delta \mu}$$

`$\text{Bid} = \text{Simplify}[\delta S VLo + (1 - \delta S) VHi]$`

$$\frac{VHi - VHi \delta + VLo \delta (1 + \mu)}{1 + \delta \mu}$$

`$\text{Simplify}[\delta S /. \delta \rightarrow \delta B]$`

$$\frac{\delta (-1 + \mu) (1 + \mu)}{-1 + \delta \mu^2}$$

Manipulation by buying at the ask and selling at the revised bid? Nope.

`$\text{Simplify}[(-\text{Ask} + \text{Bid} /. \delta \rightarrow \delta B) > 0, \{0 < \mu < 1, 0 < \delta < 1, VHi > VLo\}]$`

False

Manipulation by selling at the bid and buying at the revised ask? Nope.

`$\text{Simplify}[(\text{Bid} - \text{Ask} /. \delta \rightarrow \delta S) > 0, \{0 < \mu < 1, 0 < \delta < 1, VHi > VLo\}]$`

False



---

■ Exercise 5.3 (Informed traders get a signal, Source notebook: SequentialTrade)

```
LabelTree =  
  {V,  
   {VLo,  
    {In, {SLo, S}, {SHi, B}},  
    {Un, B, S}},  
   {VHi,  
    {In, {SLo, S}, {SHi, B}},  
    {Un, B, S}}  
}; LabelTree // ShowTree
```

```
V VLo In SLo S  
    SHi B  
    Un B  
    S  
VHi In SLo S  
    SHi B  
    Un B  
    S
```



```
Values = {γ → .1, μ → .2, δ → .3};
```

```
δB /. Values
```

```
0.371795
```

```
Ask = Simplify[δB VLo + (1 - δB) VHi]
```

$$\frac{VLo \delta (-1 + (-1 + 2 \gamma) \mu) + VHi (-1 + \delta) (1 + (-1 + 2 \gamma) \mu)}{-1 + (-1 + 2 \gamma) (-1 + 2 \delta) \mu}$$

```
δS = Pr[ExTree, VLo, S] / Pr[ExTree, S] // Simplify
```

$$\frac{\delta (1 + (-1 + 2 \gamma) \mu)}{1 + (-1 + 2 \gamma) (-1 + 2 \delta) \mu}$$

```
Bid1 = Simplify[δS VLo + (1 - δS) VHi]
```

$$\frac{VHi (-1 + \delta) (-1 + (-1 + 2 \gamma) \mu) + VLo \delta (1 + (-1 + 2 \gamma) \mu)}{1 + (-1 + 2 \gamma) (-1 + 2 \delta) \mu}$$

```
Simplify[δS /. δ → δB]
```

```
δ
```

#### ■ Exercise 5.4 (Offsetting trades, Source notebook: SequentialTrade)

A sell followed by a buy gives ... (see the analysis of the original problem, above).

```
FoldList[δCond, δ₀, {S, B}] //. δCondRule // Simplify
```

$$\left\{ \delta_0, \frac{(1 + \mu) \delta_0}{1 - \mu + 2 \mu \delta_0}, \delta_0 \right\}$$

#### ■ Exercise 7.1 (Informative noise traders, Source notebook: StrategicTrade)

As in the basic problem:

```
PRule = p → Y λ + μ;
YRule = Y → u + x;
πRule = π → (v - p) x;
```

The informed trader's profits are:

```
π /. πRule /. PRule /. YRule
```

```
x (v - (u + x) λ - μ)
```

At this point we diverge from the basic model because  $u$  and  $v$  are correlated. The projection the informed trader makes is:

$$\text{uvDist} = \text{MVN}[\{\{p_0\}, \{0\}\}, \{\{\Sigma_0, \sigma_{uv}\}, \{\sigma_{uv}, \sigma_u^2\}\}, \{v, u\}]$$

$$\begin{pmatrix} v \\ u \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ 0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & \sigma_{uv} \\ \sigma_{uv} & \sigma_u^2 \end{pmatrix} \right)$$

$$\text{uConditionalDist} = \text{MVNConditional}[\text{uvDist}, u, v]$$

$$u \sim \mathcal{N} \left( \frac{(v - p_0) \sigma_{uv}}{\Sigma_0}, \sigma_u^2 - \frac{\sigma_{uv}^2}{\Sigma_0} \right)$$

The informed trader's expected profits (conditional on  $v$ ) are:

$$\mathbf{E}\pi = \pi /. \pi_{\text{Rule}} /. p_{\text{Rule}} /. y_{\text{Rule}} /. u \rightarrow \text{GetMean}[\text{uConditionalDist}]$$

$$x \left( v - \mu - \lambda \left( x + \frac{(v - p_0) \sigma_{uv}}{\Sigma_0} \right) \right)$$

The informed trader's optimal trade is:

$$\mathbf{xOpt} = \text{First} @ \text{Simplify}[\text{Solve}[\partial_x \mathbf{E}\pi == 0, x]]$$

$$\left\{ x \rightarrow \frac{(v - \mu) \Sigma_0 + \lambda (-v + p_0) \sigma_{uv}}{2 \lambda \Sigma_0} \right\}$$

The MM conjectures that the informed trader's demand is linear in  $v$  (as above), and must figure out  $\mathbf{E}[v | y]$ :

$$\mathbf{x}_{\text{Rule}} = x \rightarrow \alpha + v \beta;$$

$$\mathbf{xEqu} = (x /. \mathbf{x}_{\text{Rule}}) == (x /. \mathbf{xOpt})$$

$$\alpha + v \beta == \frac{(v - \mu) \Sigma_0 + \lambda (-v + p_0) \sigma_{uv}}{2 \lambda \Sigma_0}$$

$$\mathbf{x}_{\text{Solutions}} = \text{Reduce}[\forall v \mathbf{xEqu} \ \&\& \ \Sigma_0 > 0 \ \&\& \ \lambda > 0, \{\alpha, \beta\}, \text{Reals}]$$

$$\Sigma_0 > 0 \ \&\& \ \lambda > 0 \ \&\& \ \alpha == \frac{-\mu \Sigma_0 + \lambda p_0 \sigma_{uv}}{2 \lambda \Sigma_0} \ \&\& \ \beta == \frac{\Sigma_0 - \lambda \sigma_{uv}}{2 \lambda \Sigma_0}$$

$$\mathbf{x}_{\text{Solutions}} = \text{Simplify} @ \text{ToRules} @ \text{Take}[\mathbf{x}_{\text{Solutions}}, -2]$$

$$\left\{ \alpha \rightarrow \frac{1}{2} \left( -\frac{\mu}{\lambda} + \frac{p_0 \sigma_{uv}}{\Sigma_0} \right), \beta \rightarrow \frac{\Sigma_0 - \lambda \sigma_{uv}}{2 \lambda \Sigma_0} \right\}$$

Now the MM must compute  $\mathbf{E}[v | y]$ :

```
MakeLinearForm[uvDist, {v, y /. YRule /. xRule}]
```

$$\begin{pmatrix} v \\ u + \alpha + v \beta \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ \alpha + \beta p_0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & \beta \Sigma_0 + \sigma_{uv} \\ \beta \Sigma_0 + \sigma_{uv} & \sigma_u^2 + \beta \sigma_{uv} + \beta (\beta \Sigma_0 + \sigma_{uv}) \end{pmatrix} \right)$$

```
vyDist = SetLabel[%, {v, y}]
```

$$\begin{pmatrix} v \\ Y \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ \alpha + \beta p_0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & \beta \Sigma_0 + \sigma_{uv} \\ \beta \Sigma_0 + \sigma_{uv} & \sigma_u^2 + \beta \sigma_{uv} + \beta (\beta \Sigma_0 + \sigma_{uv}) \end{pmatrix} \right)$$

```
vConditionalDist = MVNConditional[vyDist, v, y] // Simplify
```

$$v \sim \mathcal{N} \left( \frac{(Y - \alpha) (\beta \Sigma_0 + \sigma_{uv}) + p_0 (\sigma_u^2 + \beta \sigma_{uv})}{\beta^2 \Sigma_0 + \sigma_u^2 + 2 \beta \sigma_{uv}}, \frac{\Sigma_0 \sigma_u^2 - \sigma_{uv}^2}{\beta^2 \Sigma_0 + \sigma_u^2 + 2 \beta \sigma_{uv}} \right)$$

Market efficiency:

```
pEqu = GetMean[vConditionalDist] == (p /. PRule)
```

$$\frac{(Y - \alpha) (\beta \Sigma_0 + \sigma_{uv}) + p_0 (\sigma_u^2 + \beta \sigma_{uv})}{\beta^2 \Sigma_0 + \sigma_u^2 + 2 \beta \sigma_{uv}} == Y \lambda + \mu$$

```
r = Reduce[ForAll[y, True, pEqu], {mu, lambda}]
```

$$\beta^2 \Sigma_0 + \sigma_u^2 + 2 \beta \sigma_{uv} \neq 0 \ \&\& \ \mu == \frac{-\alpha \beta \Sigma_0 + \sigma_u^2 p_0 - \alpha \sigma_{uv} + \beta p_0 \sigma_{uv}}{\beta^2 \Sigma_0 + \sigma_u^2 + 2 \beta \sigma_{uv}} \ \&\& \ \lambda == \frac{\beta \Sigma_0 + \sigma_{uv}}{\beta^2 \Sigma_0 + \sigma_u^2 + 2 \beta \sigma_{uv}}$$

```
pSolutions = ToRules[Take[r, -2]]
```

$$\left\{ \mu \rightarrow \frac{-\alpha \beta \Sigma_0 + \sigma_u^2 p_0 - \alpha \sigma_{uv} + \beta p_0 \sigma_{uv}}{\beta^2 \Sigma_0 + \sigma_u^2 + 2 \beta \sigma_{uv}}, \lambda \rightarrow \frac{\beta \Sigma_0 + \sigma_{uv}}{\beta^2 \Sigma_0 + \sigma_u^2 + 2 \beta \sigma_{uv}} \right\}$$

Collecting the results and solving:

```
EquSet = Apply[Equal, Join[pSolutions, xSolutions], 1]
```

$$\left\{ \mu == \frac{-\alpha \beta \Sigma_0 + \sigma_u^2 p_0 - \alpha \sigma_{uv} + \beta p_0 \sigma_{uv}}{\beta^2 \Sigma_0 + \sigma_u^2 + 2 \beta \sigma_{uv}}, \lambda == \frac{\beta \Sigma_0 + \sigma_{uv}}{\beta^2 \Sigma_0 + \sigma_u^2 + 2 \beta \sigma_{uv}}, \alpha == \frac{1}{2} \left( -\frac{\mu}{\lambda} + \frac{p_0 \sigma_{uv}}{\Sigma_0} \right), \beta == \frac{\Sigma_0 - \lambda \sigma_{uv}}{2 \lambda \Sigma_0} \right\}$$

```
ModelSolutions = Simplify[Solve[EquSet, {μ, λ, α, β}], {σu2 > 0, Σ0 > 0}];
ModelSolutions // Transpose // TableForm
```

$$\begin{array}{ll} \alpha \rightarrow \frac{p_0 \left( \sigma_{uv} - \sqrt{4 \Sigma_0 \sigma_u^2 - 3 \sigma_{uv}^2} \right)}{2 \Sigma_0} & \alpha \rightarrow \frac{p_0 \left( \sigma_{uv} + \sqrt{4 \Sigma_0 \sigma_u^2 - 3 \sigma_{uv}^2} \right)}{2 \Sigma_0} \\ \mu \rightarrow p_0 & \mu \rightarrow p_0 \\ \lambda \rightarrow \frac{\Sigma_0 \left( \sigma_{uv} + \sqrt{4 \Sigma_0 \sigma_u^2 - 3 \sigma_{uv}^2} \right)}{4 \Sigma_0 \sigma_u^2 - 3 \sigma_{uv}^2 + \sigma_{uv} \sqrt{4 \Sigma_0 \sigma_u^2 - 3 \sigma_{uv}^2}} & \lambda \rightarrow \frac{\Sigma_0 \left( -\sigma_{uv} + \sqrt{4 \Sigma_0 \sigma_u^2 - 3 \sigma_{uv}^2} \right)}{-4 \Sigma_0 \sigma_u^2 + 3 \sigma_{uv}^2 + \sigma_{uv} \sqrt{4 \Sigma_0 \sigma_u^2 - 3 \sigma_{uv}^2}} \\ \beta \rightarrow \frac{-\sigma_{uv} + \sqrt{4 \Sigma_0 \sigma_u^2 - 3 \sigma_{uv}^2}}{2 \Sigma_0} & \beta \rightarrow -\frac{\sigma_{uv} + \sqrt{4 \Sigma_0 \sigma_u^2 - 3 \sigma_{uv}^2}}{2 \Sigma_0} \end{array}$$

Only the first solution can have  $\beta > 0$ , So:

```
ModelSolutions = ModelSolutions[[1]];
```

When  $\sigma_{uv} = 0$ , this reduces to the original solutions:

```
Simplify[ModelSolutions /. σuv → 0, {Σ0 > 0, σu2 > 0}]
```

$$\left\{ \alpha \rightarrow -\frac{\sigma_u^2 p_0}{\sqrt{\Sigma_0 \sigma_u^2}}, \mu \rightarrow p_0, \lambda \rightarrow \frac{\Sigma_0}{2 \sqrt{\Sigma_0 \sigma_u^2}}, \beta \rightarrow \sqrt{\frac{\sigma_u^2}{\Sigma_0}} \right\}$$

With perfect correlation...

```
AltSolution = Simplify[ModelSolutions /. σuv → √(σu2 Σ0), {Σ0 > 0, σu2 > 0}]
```

$$\left\{ \alpha \rightarrow 0, \mu \rightarrow p_0, \lambda \rightarrow \sqrt{\frac{\Sigma_0}{\sigma_u^2}}, \beta \rightarrow 0 \right\}$$

Since  $\beta = 0$ , the informed trader doesn't trade at all. The uninformed trade, though, is linear in  $v$ :

$$u_{\text{Rule}} = u \rightarrow \frac{(v - p_0) \sqrt{\sigma_u^2 \Sigma_0}}{\Sigma_0};$$

Under these conditions, the market clearing price becomes  $p = p_0 + \lambda y = v$ .

```
Simplify[pRule /. AltSolution /. yRule /. x → 0 /. uRule, {Σ0 > 0, σu2 > 0}]
```

$$p \rightarrow v$$

Also, the conditional variance is:

```
GetVariance[vConditionalDist] //. ModelSolutions /. σuv → √(σu2 Σ0)
```

$$0$$

---

**Exercise 7.2 (Informed trader gets a signal, Source notebook: StrategicTrade)**

The informed trader in the basic model has perfect information about  $v$ . Consider the case where she only gets a signal  $s$  about  $v$ . That is,  $s = v + \epsilon$  where  $\epsilon \sim N[0, \sigma_\epsilon^2]$ , independent of  $v$ . Solve the model by proceeding as in the basic case. Solve the informed trader's problem; solve the MM's problem; solve for the model parameters  $(\alpha, \beta, \mu, \lambda)$  in terms of the inputs,  $\sigma_u^2$ ,  $\Sigma_0$ , and  $\sigma_\epsilon^2$ . Interpret your results. Verify that when  $\sigma_\epsilon^2 = 0$ , you get the original model solutions.

□ *Solution*

```
PRule = p -> y λ + μ;
YRule = y -> u + x;
πRule = π -> (v - p) x;
```

Informed trader's profits:

```
π /. πRule /. PRule /. YRule
```

```
x (v - (u + x) λ - μ)
```

The informed trader gets the signal  $s$ :

```
sRule = s -> v + ε;
```

There are three random variables in this problem:

```
veuDistribution = MVN[{p0, 0, 0}, {Σ0, 0, 0}, {0, σϵ², 0}, {0, 0, σu²}], {v, ε, u}]
```

$$\begin{pmatrix} v \\ \epsilon \\ u \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & 0 & 0 \\ 0 & \sigma_\epsilon^2 & 0 \\ 0 & 0 & \sigma_u^2 \end{pmatrix} \right)$$

We can rework this into a distribution for  $v$ ,  $s$ ,  $u$ :

```
MakeLinearForm[veuDistribution, {v, s /. sRule, u}]
```

$$\begin{pmatrix} v \\ v + \epsilon \\ u \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ p_0 \\ 0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & \Sigma_0 & 0 \\ \Sigma_0 & \Sigma_0 + \sigma_\epsilon^2 & 0 \\ 0 & 0 & \sigma_u^2 \end{pmatrix} \right)$$

```
vsuDistribution = SetLabel[%, {v, s, u}]
```

$$\begin{pmatrix} v \\ s \\ u \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ p_0 \\ 0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & \Sigma_0 & 0 \\ \Sigma_0 & \Sigma_0 + \sigma_\epsilon^2 & 0 \\ 0 & 0 & \sigma_u^2 \end{pmatrix} \right)$$

The informed trader forms the conditional distribution of  $v$  based on his signal:

```
vConditionalDistInf = MVNConditional[vsuDistribution, v, s]
```

$$v \sim \mathcal{N} \left( \frac{\Sigma_0 (s - p_0)}{\Sigma_0 + \sigma_\epsilon^2} + p_0, \Sigma_0 - \frac{\Sigma_0^2}{\Sigma_0 + \sigma_\epsilon^2} \right)$$

The expected profits are developed from:

```
 $\pi / \cdot \pi_{\text{Rule}} / \cdot P_{\text{Rule}} / \cdot Y_{\text{Rule}}$ 
```

```
 $x (v - (u + x) \lambda - \mu)$ 
```

... substituting in the conditional mean for v:

```
E $\pi$  =  $\pi / \cdot \pi_{\text{Rule}} / \cdot P_{\text{Rule}} / \cdot Y_{\text{Rule}} / \cdot u \rightarrow 0 / \cdot v \rightarrow \text{GetMean}[v\text{ConditionalDistInf}]$ 
```

$$x \left( -x \lambda - \mu + \frac{\Sigma_0 (s - p_0)}{\Sigma_0 + \sigma_\epsilon^2} + p_0 \right)$$

The informed trader maximizes expected profits by trading x:

```
xOpt = First @ Simplify[Solve[ $\partial_x E\pi = 0, x$ ]]
```

$$\left\{ x \rightarrow \frac{s \Sigma_0 - \mu (\Sigma_0 + \sigma_\epsilon^2) + \sigma_\epsilon^2 p_0}{2 \lambda (\Sigma_0 + \sigma_\epsilon^2)} \right\}$$

The MM conjectures that the informed trader's demand is linear in s:

```
 $x_{\text{Rule}} = x \rightarrow \alpha + s \beta;$ 
```

Knowing the optimization process that the informed trader followed, the MM can solve for  $\alpha$  and  $\beta$ :

```
xEqu = (x / . xRule) == (x / . xOpt)
```

$$\alpha + s \beta == \frac{s \Sigma_0 - \mu (\Sigma_0 + \sigma_\epsilon^2) + \sigma_\epsilon^2 p_0}{2 \lambda (\Sigma_0 + \sigma_\epsilon^2)}$$

```
xSolutions = Reduce[ $\forall s, xEqu \ \&\& \ \Sigma_0 > 0 \ \&\& \ \sigma_\epsilon^2 > 0 \ \&\& \ \lambda > 0 \ \&\& \ s \neq 0, \{\alpha, \beta\}, \text{Reals}$ ]
```

$$\sigma_\epsilon^2 > 0 \ \&\& \ \Sigma_0 > 0 \ \&\& \ \lambda > 0 \ \&\& \ \left( \left( s < 0 \ \&\& \ \alpha == \frac{-\mu \Sigma_0 - \mu \sigma_\epsilon^2 + \sigma_\epsilon^2 p_0}{2 \lambda \Sigma_0 + 2 \lambda \sigma_\epsilon^2} \ \&\& \ \beta == \frac{\Sigma_0}{2 \lambda \Sigma_0 + 2 \lambda \sigma_\epsilon^2} \right) \parallel \right. \\ \left. \left( s > 0 \ \&\& \ \alpha == \frac{-\mu \Sigma_0 - \mu \sigma_\epsilon^2 + \sigma_\epsilon^2 p_0}{2 \lambda \Sigma_0 + 2 \lambda \sigma_\epsilon^2} \ \&\& \ \beta == \frac{\Sigma_0}{2 \lambda \Sigma_0 + 2 \lambda \sigma_\epsilon^2} \right) \right)$$



```
xSolutions = Simplify @ ToRules @ Take[xSolutions[[4, 1]], -2]
```

$$\left\{ \alpha \rightarrow \frac{-\mu (\Sigma_0 + \sigma_\epsilon^2) + \sigma_\epsilon^2 p_0}{2 \lambda (\Sigma_0 + \sigma_\epsilon^2)}, \beta \rightarrow \frac{\Sigma_0}{2 \lambda \Sigma_0 + 2 \lambda \sigma_\epsilon^2} \right\}$$

Now the MM must figure out  $E[V | Y = y]$ . This is a little more involved than in the original problem because the informed trader's demand is conditioned on  $s$ . The joint distribution of  $v$  and  $y = u + \alpha + s\beta$  is:

```
MakeLinearForm[vsuDistribution, {v, y /. yRule /. xRule}]
```

$$\begin{pmatrix} v \\ u + \alpha + s\beta \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ \alpha + \beta p_0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & \beta \Sigma_0 \\ \beta \Sigma_0 & \sigma_u^2 + \beta^2 (\Sigma_0 + \sigma_\epsilon^2) \end{pmatrix} \right)$$

... and relabeling:

```
vyDistribution = SetLabel[%, {v, y}]
```

$$\begin{pmatrix} v \\ y \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ \alpha + \beta p_0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & \beta \Sigma_0 \\ \beta \Sigma_0 & \sigma_u^2 + \beta^2 (\Sigma_0 + \sigma_\epsilon^2) \end{pmatrix} \right)$$

So the distribution of  $v$  (conditional on  $y$ ) is:

```
vConditionalDistributionMM = MVNConditional[vyDistribution, v, y]
```

$$v \sim \mathcal{N} \left( p_0 + \frac{\beta \Sigma_0 (y - \alpha - \beta p_0)}{\sigma_u^2 + \beta^2 (\Sigma_0 + \sigma_\epsilon^2)}, \Sigma_0 - \frac{\beta^2 \Sigma_0^2}{\sigma_u^2 + \beta^2 (\Sigma_0 + \sigma_\epsilon^2)} \right)$$

Market efficiency requires

```
pEqu = GetMean[vConditionalDistributionMM] == (p /. pRule)
```

$$p_0 + \frac{\beta \Sigma_0 (y - \alpha - \beta p_0)}{\sigma_u^2 + \beta^2 (\Sigma_0 + \sigma_\epsilon^2)} == y \lambda + \mu$$

Solving:

```
pSolutions = Reduce[Vy pEqu && \Sigma_0 > 0 && \sigma_\epsilon^2 > 0 && \sigma_u^2 > 0, {\mu, \lambda}, Reals]
```

$$\sigma_\epsilon^2 > 0 \&\& \Sigma_0 > 0 \&\& \sigma_u^2 > 0 \&\& \mu == \frac{-\alpha \beta \Sigma_0 + \sigma_u^2 p_0 + \beta^2 \sigma_\epsilon^2 p_0}{\beta^2 \Sigma_0 + \sigma_u^2 + \beta^2 \sigma_\epsilon^2} \&\& \lambda == \frac{\beta \Sigma_0}{\beta^2 \Sigma_0 + \sigma_u^2 + \beta^2 \sigma_\epsilon^2}$$

```
pSolutions = Simplify @ ToRules @ Take[pSolutions, -2]
```

$$\left\{ \mu \rightarrow \frac{-\alpha \beta \Sigma_0 + (\sigma_u^2 + \beta^2 \sigma_\epsilon^2) p_0}{\sigma_u^2 + \beta^2 (\Sigma_0 + \sigma_\epsilon^2)}, \lambda \rightarrow \frac{\beta \Sigma_0}{\sigma_u^2 + \beta^2 (\Sigma_0 + \sigma_\epsilon^2)} \right\}$$

Collecting the results and solving:

```
EquationSet = Apply[Equal, Join[pSolutions, xSolutions], 1]
```

$$\left\{ \mu = \frac{-\alpha \beta \Sigma_0 + (\sigma_u^2 + \beta^2 \sigma_\epsilon^2) p_0}{\sigma_u^2 + \beta^2 (\Sigma_0 + \sigma_\epsilon^2)}, \lambda = \frac{\beta \Sigma_0}{\sigma_u^2 + \beta^2 (\Sigma_0 + \sigma_\epsilon^2)}, \right.$$

$$\left. \alpha = \frac{-\mu (\Sigma_0 + \sigma_\epsilon^2) + \sigma_\epsilon^2 p_0}{2 \lambda (\Sigma_0 + \sigma_\epsilon^2)}, \beta = \frac{\Sigma_0}{2 \lambda \Sigma_0 + 2 \lambda \sigma_\epsilon^2} \right\}$$

```
ModelSolutions =
```

```
Simplify[Solve[EquationSet, {\mu, \lambda, \alpha, \beta}], {\Sigma_0 > 0, \sigma_u^2 > 0, \sigma_\epsilon^2 > 0}] // First
```

$$\left\{ \alpha \rightarrow -\sqrt{\frac{\sigma_u^2}{\Sigma_0 + \sigma_\epsilon^2}} p_0, \mu \rightarrow p_0, \lambda \rightarrow \frac{\Sigma_0}{2 \sqrt{\sigma_u^2 (\Sigma_0 + \sigma_\epsilon^2)}}, \beta \rightarrow \sqrt{\frac{\sigma_u^2}{\Sigma_0 + \sigma_\epsilon^2}} \right\}$$

To recover the original solutions:

```
ModelSolutions /. \sigma_\epsilon^2 \to 0
```

$$\left\{ \alpha \rightarrow -\sqrt{\frac{\sigma_u^2}{\Sigma_0}} p_0, \mu \rightarrow p_0, \lambda \rightarrow \frac{\Sigma_0}{2 \sqrt{\Sigma_0 \sigma_u^2}}, \beta \rightarrow \sqrt{\frac{\sigma_u^2}{\Sigma_0}} \right\}$$

Given the price (or equivalently the total order flow), the variance of  $v$  is:

```
GetVariance[vConditionalDistributionMM]
```

$$\Sigma_0 - \frac{\beta^2 \Sigma_0^2}{\sigma_u^2 + \beta^2 (\Sigma_0 + \sigma_\epsilon^2)}$$

As we degrade the signal (increase  $\sigma_\epsilon^2$ ), the conditional variance approaches the unconditional variance.

### ■ Exercise 7.3 (Broker piggy-backs on informed trader, Source notebook: StrategicTrade)

□ *Solution*

$$p_{\text{Rule}} = p \rightarrow y \lambda + \mu;$$

But now the order flow includes the broker's order flow  $\gamma x$ .

$$y_{\text{Rule}} = y \rightarrow u + x (1 + \gamma);$$

The informed trader's profits are:

$$\pi_{\text{Rule}} = \pi \rightarrow (v - p) x;$$

Substituting in for the price conjecture and  $y$ :

$$\pi / \cdot \pi_{\text{Rule}} / \cdot P_{\text{Rule}} / \cdot Y_{\text{Rule}}$$

$$x (v - (u + x (1 + \gamma)) \lambda - \mu)$$

The expected profits (conditional on  $v$ ) are  $E\pi$ :

$$E\pi = \text{Simplify}[\pi / \cdot \pi_{\text{Rule}} / \cdot P_{\text{Rule}} / \cdot Y_{\text{Rule}} / \cdot u \rightarrow 0]$$

$$x (v - x (1 + \gamma) \lambda - \mu)$$

The optimal quantity is:

$$x_{\text{Opt}} = \text{First} @ \text{Solve}[\partial_x E\pi == 0, x]$$

$$\left\{ x \rightarrow \frac{v - \mu}{2 (1 + \gamma) \lambda} \right\}$$

$$x_{\text{Rule}} = x \rightarrow \alpha + v \beta;$$

$$x_{\text{Equ}} = (x / \cdot x_{\text{Rule}}) == (x / \cdot x_{\text{Opt}})$$

$$\alpha + v \beta == \frac{v - \mu}{2 (1 + \gamma) \lambda}$$

Solving:

$$x_{\text{Solutions}} = \text{Reduce}[\forall v \ x_{\text{Equ}} \ \&\& \ \lambda > 0 \ \&\& \ \gamma > 0, \{\alpha, \beta\}, \text{Reals}]$$

$$\lambda > 0 \ \&\& \ \gamma > 0 \ \&\& \ \alpha == -\frac{\mu}{2 \lambda + 2 \gamma \lambda} \ \&\& \ \beta == \frac{1}{2 \lambda + 2 \gamma \lambda}$$

$$x_{\text{Solutions}} = \text{Simplify} @ \text{ToRules} @ \text{Take}[x_{\text{Solutions}}, -2]$$

$$\left\{ \alpha \rightarrow -\frac{\mu}{2 \lambda + 2 \gamma \lambda}, \beta \rightarrow \frac{1}{2 \lambda + 2 \gamma \lambda} \right\}$$

As always, the MM must figure out  $E[v | \gamma]$ . Starting from the original joint distribution:

$$uv\text{Dist} = \text{MVN}[\{\{p_0\}, \{0\}\}, \{\{\Sigma_0, 0\}, \{0, \sigma_u^2\}\}, \{v, u\}]$$

$$\begin{pmatrix} v \\ u \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ 0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & 0 \\ 0 & \sigma_u^2 \end{pmatrix} \right)$$

Now, though, we have a more complicated form for  $\gamma$ :  $\gamma = u + (\alpha + v \beta) (1 + \gamma)$ . The joint distribution of  $v$  and  $\gamma$  is:

```
MakeLinearForm[uvDist, {v, y /. YRule /. xRule}]
```

$$\begin{pmatrix} v \\ u + (\alpha + v\beta)(1 + \gamma) \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ (\alpha + v\beta)(1 + \gamma) - v(\beta + \beta\gamma) + (\beta + \beta\gamma)p_0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & (\beta + \beta\gamma)\Sigma_0 \\ (\beta + \beta\gamma)\Sigma_0 & (\beta + \beta\gamma)^2\Sigma_0 + \sigma_u^2 \end{pmatrix} \right)$$

...relabeling:

```
vyDistribution = SetLabel[%, {v, y}]
```

$$\begin{pmatrix} v \\ y \end{pmatrix} \sim \mathcal{N} \left( \begin{pmatrix} p_0 \\ (\alpha + v\beta)(1 + \gamma) - v(\beta + \beta\gamma) + (\beta + \beta\gamma)p_0 \end{pmatrix}, \begin{pmatrix} \Sigma_0 & (\beta + \beta\gamma)\Sigma_0 \\ (\beta + \beta\gamma)\Sigma_0 & (\beta + \beta\gamma)^2\Sigma_0 + \sigma_u^2 \end{pmatrix} \right)$$

The conditional distribution is:

```
vConditionalDist = MVNConditional[vyDistribution, v, y] // Simplify
```

$$v \sim \mathcal{N} \left( \frac{-\beta(1 + \gamma)(-y + \alpha + \alpha\gamma)\Sigma_0 + \sigma_u^2 p_0}{\beta^2(1 + \gamma)^2\Sigma_0 + \sigma_u^2}, \frac{\Sigma_0 \sigma_u^2}{\beta^2(1 + \gamma)^2\Sigma_0 + \sigma_u^2} \right)$$

Market efficiency:

```
pEqu = GetMean[vConditionalDist] == (p /. PRule)
```

$$\frac{-\beta(1 + \gamma)(-y + \alpha + \alpha\gamma)\Sigma_0 + \sigma_u^2 p_0}{\beta^2(1 + \gamma)^2\Sigma_0 + \sigma_u^2} = y\lambda + \mu$$

```
P Solutions = Reduce[Vy pEqu, {mu, lambda}]
```

$$\beta^2 \Sigma_0 + 2\beta^2 \gamma \Sigma_0 + \beta^2 \gamma^2 \Sigma_0 + \sigma_u^2 \neq 0 \ \&\& \ \mu = \frac{-\alpha\beta\Sigma_0 - 2\alpha\beta\gamma\Sigma_0 - \alpha\beta\gamma^2\Sigma_0 + \sigma_u^2 p_0}{\beta^2 \Sigma_0 + 2\beta^2 \gamma \Sigma_0 + \beta^2 \gamma^2 \Sigma_0 + \sigma_u^2} \ \&\& \ \lambda = \frac{\beta\Sigma_0 + \beta\gamma\Sigma_0}{\beta^2 \Sigma_0 + 2\beta^2 \gamma \Sigma_0 + \beta^2 \gamma^2 \Sigma_0 + \sigma_u^2}$$

```
P Solutions = Simplify @ ToRules[Take[P Solutions, -2]]
```

$$\left\{ \mu \rightarrow \frac{-\alpha\beta(1 + \gamma)^2 \Sigma_0 + \sigma_u^2 p_0}{\beta^2(1 + \gamma)^2 \Sigma_0 + \sigma_u^2}, \lambda \rightarrow \frac{\beta(1 + \gamma)\Sigma_0}{\beta^2(1 + \gamma)^2 \Sigma_0 + \sigma_u^2} \right\}$$

```
EquationSet = Apply[Equal, Join[P Solutions, xSolutions], 1]
```

$$\left\{ \mu = \frac{-\alpha\beta(1 + \gamma)^2 \Sigma_0 + \sigma_u^2 p_0}{\beta^2(1 + \gamma)^2 \Sigma_0 + \sigma_u^2}, \lambda = \frac{\beta(1 + \gamma)\Sigma_0}{\beta^2(1 + \gamma)^2 \Sigma_0 + \sigma_u^2}, \alpha = -\frac{\mu}{2\lambda + 2\gamma\lambda}, \beta = \frac{1}{2\lambda + 2\gamma\lambda} \right\}$$

```
Model_solutions = Simplify[Solve[EquationSet, {μ, λ, α, β}], {Σ₀ > 0, σᵤ² > 0}] // First
```

$$\left\{ \alpha \rightarrow -\frac{\sqrt{\frac{\sigma_u^2}{\Sigma_0}} p_0}{1 + \gamma}, \mu \rightarrow p_0, \lambda \rightarrow \frac{1}{2} \sqrt{\frac{\Sigma_0}{\sigma_u^2}}, \beta \rightarrow \frac{\sqrt{\frac{\sigma_u^2}{\Sigma_0}}}{1 + \gamma} \right\}$$

To recover the original solution ...

```
Model_solutions /. γ → 0
```

$$\left\{ \alpha \rightarrow -\sqrt{\frac{\sigma_u^2}{\Sigma_0}} p_0, \mu \rightarrow p_0, \lambda \rightarrow \frac{1}{2} \sqrt{\frac{\Sigma_0}{\sigma_u^2}}, \beta \rightarrow \sqrt{\frac{\sigma_u^2}{\Sigma_0}} \right\}$$

The expected profits are

```
Simplify[PowerExpand[Eπ /. xRule /. Model_solutions]]
```

$$\frac{\sqrt{\sigma_u^2} (v - p_0)^2}{2 (1 + \gamma) \sqrt{\Sigma_0}}$$

The informed trader's demand is:

```
Simplify[xRule /. Model_solutions]
```

$$x \rightarrow \frac{\sqrt{\frac{\sigma_u^2}{\Sigma_0}} (v - p_0)}{1 + \gamma}$$

Since  $\gamma > 0$ , the informed trader's expected profits are lower. Also, she fades her demand to take into account the crooked broker. The informativeness of the price is:

```
GetVariance[vConditionalDist] /. Model_solutions
```

$$\frac{\Sigma_0}{2}$$

Unchanged, relative to the original model.

### ■ Exercise 8.1 (Source notebook: RollBasicAndGeneralized)

The model is observationally equivalent to one in which there is no lag on the efficient price. The autocovariances and moving average representation are the same.

---

■ Exercise 8.2 (Source notebook: RollBasicAndGeneralized)

By rearranging, the model can be written as  $(1 - (1 - \alpha) L) p_t = \alpha m_t$ . Taking first differences  
 $(1 - (1 - \alpha) L) \Delta p_t = \epsilon_t = \alpha w_t$  So:

$$\phi[L] := 1 - (1 - \alpha) L$$

The MA representation is  $\Delta p_t = \theta(L) \epsilon_t$  where  $\theta(L) = \phi(L)^{-1}$ . Furthermore  $\theta(1)^2 =$

$$\phi[1]^{-2}$$

$$\frac{1}{\alpha^2}$$

Since  $\sigma_\epsilon^2 = \alpha^2 \sigma_w^2$ ,  $\theta(1)^2 \sigma_\epsilon^2 = \sigma_w^2$

---

■ Exercise 8.3 (Source notebook: RollBasicAndGeneralized)

Over five-minute intervals

$$\sigma_{\text{Rule}} = \sigma_\epsilon^2 \rightarrow 0.00001;$$

$$\theta[L] := 1 - 0.3 L + 0.1 L^2$$

Random-walk variance:

$$\sqrt{\theta[1]^2 \sigma_\epsilon^2 / \sigma_{\text{Rule}}}$$

$$0.00252982$$

Over one day:

$$\sqrt{6 * 12 * \theta[1]^2 \sigma_\epsilon^2 / \sigma_{\text{Rule}}}$$

$$0.0214663$$

i.e., about 2%

For the pricing error variance, the  $C_i$  coefficients are generally:

$$C_{\text{Rule}} = C[\theta, i] := \sum_{j=i+1}^{\text{Exponent}[\theta[L], L]} -\text{Coefficient}[\theta[L], L, j];$$

and here ...

```
Table[C[θ, i], {i, 0, 2}] /. CRule
```

```
{0.2, -0.1, 0}
```

```

$$\sqrt{\sum_{i=0}^{\text{Exponent}[\theta[L], L]-1} C[\theta, i]^2 \sigma_\epsilon^2 / \cdot C_{\text{Rule}} / \cdot \sigma_{\text{Rule}}}$$

```

```
0.000707107
```

i.e., about seven basis points

#### ■ Exercise 8.4 (Source notebook: RollBasicAndGeneralized)

The structural model is:

$$m_t = m_{t-1} + w_t$$

$$w_t = \lambda q_t + u_t$$

$$p_t = m_{t-1} + c q_t$$

Notice that the price is determined with respect to *lagged* value of the implicit efficient price.

(a) Using the structural representation, determine the  $\Delta p_t$  autocovariances  $\gamma_0$ ,  $\gamma_1$  and verify that  $\gamma_2 = 0$ .

In this and the following parts, assume that  $c = 2$  and  $\lambda = 1$ .

(b) Verify that autocovariances are the same as the autocovariances for the (statistical) MA(1) model

$\Delta p_t = \epsilon_t + \theta$  where

$$\sigma_\epsilon^2 = \frac{1}{2} \left( \sigma_u^2 + \sqrt{(\sigma_u^2 + 1)(\sigma_u^2 + 9)} + 5 \right)$$

and

$$\theta = \frac{1}{4} \left( -\sigma_u^2 + \sqrt{(\sigma_u^2 + 1)(\sigma_u^2 + 9)} - 5 \right)$$

(c) Verify that  $\sigma_w^2 = (1 + \theta)^2 \sigma_\epsilon^2$ .

(d) Compute (in terms of the MA parameters) the lower bound for  $\sigma_s^2$  where  $s_t = p_t - m_t$ . Verify that the lower bound is exact when  $\sigma_u^2 = 0$ .

□ Analysis

```
nValues = {c -> 2, λ -> 1};
```

```
mRule = m_t_ -> m_{t-1} + w_t;
```

```
wRule = w_t_ -> λ q_t + u_t;
```

```
pRule = p_t_ -> m_{t-1} + c q_t;
```

Pricing error  $s_t =$

$$p_t - m_t / p_{Rule} / m_t \rightarrow (m_t / m_{Rule}) / w_{Rule}$$

$$c q_t - \lambda q_t - u_t$$

This implies that the pricing error variance is

$$(c - \lambda)^2 + \sigma_u^2 / nValues$$

$$1 + \sigma_u^2$$

Price changes:

$$\Delta p_{Rule} = \Delta p_t \rightarrow (p_t / p_{Rule} / m_{Rule} / w_{Rule}) - (p_{t-1} / p_{Rule});$$

$$\Delta p_t / \Delta p_{Rule}$$

$$-c q_{-1+t} + \lambda q_{-1+t} + c q_t + u_{-1+t}$$

$\text{Var}[\Delta p_t] = \gamma_0$ :

$$\mathcal{E}[\text{Expand}[\Delta p_t^2 / \Delta p_{Rule}]] // \mathcal{E}_{Rules}$$

$$2 c^2 - 2 c \lambda + \lambda^2 + \sigma_u^2$$

$$2 c^2 - 2 \lambda c + \lambda^2 + \sigma_u^2$$

$$2 c^2 - 2 c \lambda + \lambda^2 + \sigma_u^2$$

$\text{Cov}[\Delta p_t, \Delta p_{t-1}] = \gamma_1$ :

$$\mathcal{E}[\text{Expand}[\Delta p_t \Delta p_{t-1} / \Delta p_{Rule}]] // \mathcal{E}_{Rules}$$

$$-c^2 + c \lambda$$

$\text{Cov}[\Delta p_t, \Delta p_{t-2}] = \gamma_2$ :

$$\mathcal{E}[\text{Expand}[\Delta p_t \Delta p_{t-2} / \Delta p_{Rule}]] // \mathcal{E}_{Rules}$$

$$0$$

Summarize the first two autocovariances in terms of the structural parameters:

$$\gamma_{\text{Structural}_{Rules}} = \{\gamma_0 \rightarrow 2 c^2 - 2 \lambda c + \lambda^2 + \sigma_u^2, \gamma_1 \rightarrow -c^2 + c \lambda\};$$

$$\gamma_{\text{Structural}_{Rules}} // \text{TableForm}$$

$$\gamma_0 \rightarrow 2 c^2 - 2 c \lambda + \lambda^2 + \sigma_u^2$$

$$\gamma_1 \rightarrow -c^2 + c \lambda$$

Now evaluate  $\text{Var}[w_t] = \sigma_w^2$ :



```
 $\mathcal{E}[\text{Expand}[w_t^2 /. w_{\text{Rule}}]] // . \mathcal{E}_{\text{Rules}}$ 
```

$$\lambda^2 + \sigma_u^2$$

The autocovariances computed from the statistical and structural representations must agree. The autocovariances for the MA(1) process  $\Delta p_t = \epsilon_t + \theta \epsilon_{t-1}$  are:

```
 $\gamma_{\text{StatisticalRules}} = \{\gamma_0 \rightarrow (\theta^2 + 1) \sigma_\epsilon^2, \gamma_1 \rightarrow \theta \sigma_\epsilon^2\}; \gamma_{\text{StatisticalRules}} // \text{TableForm}$ 
```

$$\gamma_0 \rightarrow (1 + \theta^2) \sigma_\epsilon^2$$

$$\gamma_1 \rightarrow \theta \sigma_\epsilon^2$$

```
 $\text{StatStructEqu} = \text{Apply}[\text{Equal}, \text{Join}[\gamma_{\text{StatisticalRules}}, \gamma_{\text{StructuralRules}}], \{1\}];$   
 $\text{StatStructEqu} // \text{TableForm}$ 
```

$$\gamma_0 == (1 + \theta^2) \sigma_\epsilon^2$$

$$\gamma_1 == \theta \sigma_\epsilon^2$$

$$\gamma_0 == 2 c^2 - 2 c \lambda + \lambda^2 + \sigma_u^2$$

$$\gamma_1 == -c^2 + c \lambda$$

which implies:

```
 $\text{sol} = \text{Solve}[\text{StatStructEqu}, \{\theta, \sigma_\epsilon^2\}, \{\gamma_0, \gamma_1\}] // \text{Simplify}$ 
```

$$\left\{ \left\{ \sigma_\epsilon^2 \rightarrow \frac{1}{2} \left( 2 c^2 - 2 c \lambda + \lambda^2 + \sigma_u^2 - \sqrt{\lambda^2 + \sigma_u^2} \sqrt{4 c^2 - 4 c \lambda + \lambda^2 + \sigma_u^2} \right), \right. \right.$$

$$\left. \theta \rightarrow - \frac{2 c^2 - 2 c \lambda + \lambda^2 + \sigma_u^2 + \sqrt{\lambda^2 + \sigma_u^2} \sqrt{4 c^2 - 4 c \lambda + \lambda^2 + \sigma_u^2}}{2 c^2 - 2 c \lambda} \right\},$$

$$\left\{ \sigma_\epsilon^2 \rightarrow \frac{1}{2} \left( 2 c^2 - 2 c \lambda + \lambda^2 + \sigma_u^2 + \sqrt{\lambda^2 + \sigma_u^2} \sqrt{4 c^2 - 4 c \lambda + \lambda^2 + \sigma_u^2} \right), \right.$$

$$\left. \theta \rightarrow - \frac{2 c^2 - 2 c \lambda + \lambda^2 + \sigma_u^2 - \sqrt{\lambda^2 + \sigma_u^2} \sqrt{4 c^2 - 4 c \lambda + \lambda^2 + \sigma_u^2}}{2 c^2 - 2 c \lambda} \right\} \left. \right\}$$

```
 $\text{InvertibleSolution} = \text{sol}[[2]]$ 
```

$$\left\{ \sigma_\epsilon^2 \rightarrow \frac{1}{2} \left( 2 c^2 - 2 c \lambda + \lambda^2 + \sigma_u^2 + \sqrt{\lambda^2 + \sigma_u^2} \sqrt{4 c^2 - 4 c \lambda + \lambda^2 + \sigma_u^2} \right), \right.$$

$$\left. \theta \rightarrow - \frac{2 c^2 - 2 c \lambda + \lambda^2 + \sigma_u^2 - \sqrt{\lambda^2 + \sigma_u^2} \sqrt{4 c^2 - 4 c \lambda + \lambda^2 + \sigma_u^2}}{2 c^2 - 2 c \lambda} \right\}$$

```
 $\text{FullSimplify}[\text{InvertibleSolution} /. \text{nValues}, \{\lambda > 0, \sigma_u^2 > 0, c > 0\}]$ 
```

$$\left\{ \sigma_\epsilon^2 \rightarrow \frac{1}{2} \left( 5 + \sigma_u^2 + \sqrt{(1 + \sigma_u^2)(9 + \sigma_u^2)} \right), \theta \rightarrow \frac{1}{4} \left( -5 - \sigma_u^2 + \sqrt{(1 + \sigma_u^2)(9 + \sigma_u^2)} \right) \right\}$$

```
Simplify [(1 +  $\theta$ )2  $\sigma_\epsilon^2$  /. InvertibleSolution]
```

$$\lambda^2 + \sigma_u^2$$

i.e., the coefficient of  $\epsilon_t$  is the same in both representations.

```
Simplify[ $\theta^2 \sigma_\epsilon^2$  /. InvertibleSolution /. nValues, { $\lambda > 0$ ,  $\sigma_u^2 > 0$ ,  $c > 0$ }]
```

$$\frac{1}{2} \left( 5 + \sigma_u^2 - \sqrt{(1 + \sigma_u^2)(9 + \sigma_u^2)} \right)$$

```
Simplify[ $\theta^2 \sigma_\epsilon^2$  /. InvertibleSolution /. nValues /.  $\sigma_u^2 \rightarrow 0$ , { $\lambda > 0$ ,  $\sigma_u^2 > 0$ ,  $c > 0$ }]
```

$$1$$

```
Solve[( $\theta^2 \sigma_\epsilon^2$  /. InvertibleSolution) == (c -  $\lambda$ )2 +  $\sigma_u^2$ ,  $\sigma_u^2$ ]
```

$$\{\{\sigma_u^2 \rightarrow 0\}\}$$

```
InvertibleSolution /. nValues /.  $\sigma_u^2 \rightarrow 0$  // Simplify
```

$$\left\{ \sigma_\epsilon^2 \rightarrow 4, \theta \rightarrow -\frac{1}{2} \right\}$$

## ■ Exercise 9.1 (Glosten and Harris, Source notebook: MultivariateMicrostructureModels)

Definitions:

$$m_{\text{Rule}} = m_t \rightarrow m_{t-1} + w_t ;$$

$$w_{\text{Rule}} = w_t \rightarrow \lambda_0 q_t + \lambda_1 Q_t + u_t ;$$

$$p_{\text{Rule}} = p_t \rightarrow m_t + c_1 q_t + c_2 Q_t ;$$

With these definitions,  $m_t$ ,  $w_t$  and  $p_t$  are (respectively):

```
TableForm[{m_t /. mRule, w_t /. wRule, p_t /. pRule}]
```

$$m_{-1+t} + w_t$$

$$u_t + q_t \lambda_0 + Q_t \lambda_1$$

$$m_t + c_1 q_t + c_2 Q_t$$

The price change at time  $t$  is  $\Delta p_t =$

$$\Delta p_{\text{Rule}} = \Delta p_t \rightarrow (p_t /. p_{\text{Rule}} /. m_{\text{Rule}} /. w_{\text{Rule}}) - (p_{t-1} /. p_{\text{Rule}}) ;$$

```
Simplify[ $\Delta p_t$  /.  $\Delta p_{\text{Rule}}$ ]
```

$$c_1 (-q_{-1+t} + q_t) + c_2 (-Q_{-1+t} + Q_t) + u_t + q_t \lambda_0 + Q_t \lambda_1$$

The vector of variables is:



```

ΩRule = Ω → ({{σu2, 0, 0}, {0, 1, σq,Q}, {0, σq,Q, σQ2}} /. σq,Q → √(2 σQ2 / π);
Map[MatrixForm, ΩRule, 1]

```

$$\Omega \rightarrow \begin{pmatrix} \sigma_u^2 & 0 & 0 \\ 0 & 1 & \sqrt{\frac{2}{\pi}} \sqrt{\sigma_Q^2} \\ 0 & \sqrt{\frac{2}{\pi}} \sqrt{\sigma_Q^2} & \sigma_Q^2 \end{pmatrix}$$

The random-walk variance is  $\sigma_w^2 =$

```

Simplify[(θ0 + θ1).Ω.Transpose[θ0 + θ1] /. θRules /. ΩRule, {σQ > 0, σ- ∈ Reals}][[1, 1]]

```

$$\sigma_u^2 + \lambda_0^2 + 2 \sqrt{\frac{2}{\pi}} \sqrt{\sigma_Q^2} \lambda_0 \lambda_1 + \sigma_Q^2 \lambda_1^2$$

□ *Decomposition with  $q_t$  first:*

```

F1 = Simplify[Permute[CholeskyDecomposition[Permute[Ω /. ΩRule, {2, 3, 1}]],
  {3, 1, 2}], {σQ2 > 0, σu2 > 0}];
F1 // MatrixForm

```

$$\begin{pmatrix} \sqrt{\sigma_u^2} & 0 & 0 \\ 0 & 1 & \sqrt{\frac{2}{\pi}} \sqrt{\sigma_Q^2} \\ 0 & 0 & \sqrt{\frac{-2+\pi}{\pi}} \sqrt{\sigma_Q^2} \end{pmatrix}$$

```

VarDecomp1 = ((θ0 + θ1).Transpose[F1] /. θRules // Simplify)[[1]]

```

$$\{\sqrt{\sigma_u^2}, \lambda_0 + \sqrt{\frac{2}{\pi}} \sqrt{\sigma_Q^2} \lambda_1, \sqrt{\frac{-2+\pi}{\pi}} \sqrt{\sigma_Q^2} \lambda_1\}$$

The variance components corresponding to  $u_t$ ,  $q_t$  and  $Q_t$  are:

```

{VarDecomp12 // Simplify} // TableForm

```

$$\sigma_u^2 \left( \lambda_0 + \sqrt{\frac{2}{\pi}} \sqrt{\sigma_Q^2} \lambda_1 \right)^2 \quad \frac{(-2+\pi) \sigma_Q^2 \lambda_1^2}{\pi}$$

Verify that they add up to the correct  $\sigma_w^2$ :

```
Plus @@ VarDecomp12 // Simplify
```

$$\sigma_u^2 + \lambda_0^2 + 2 \sqrt{\frac{2}{\pi}} \sqrt{\sigma_Q^2} \lambda_0 \lambda_1 + \sigma_Q^2 \lambda_1^2$$

□ *Decomposition with  $Q_t$  first:*

```
F2 = Simplify[Permute[CholeskyDecomposition[Permute[Ω /. ΩRule, {3, 2, 1}]],
  {3, 2, 1}], {σ_Q > 0, σ_u > 0}];
F2 // MatrixForm
```

$$\begin{pmatrix} \sqrt{\sigma_u^2} & 0 & 0 \\ 0 & \sqrt{\frac{-2+\pi}{\pi}} & 0 \\ 0 & \sqrt{\frac{2}{\pi}} & \sqrt{\sigma_Q^2} \end{pmatrix}$$

```
VarDecomp2 = ((θ_0 + θ_1).Transpose[F2] /. θRules // Simplify)[[1]]
```

$$\left\{ \sqrt{\sigma_u^2}, \sqrt{\frac{-2+\pi}{\pi}} \lambda_0, \sqrt{\frac{2}{\pi}} \lambda_0 + \sqrt{\sigma_Q^2} \lambda_1 \right\}$$

```
{VarDecomp22} // Simplify // TableForm
```

$$\sigma_u^2 \frac{(-2+\pi) \lambda_0^2}{\pi} \left( \sqrt{\frac{2}{\pi}} \lambda_0 + \sqrt{\sigma_Q^2} \lambda_1 \right)^2$$

... and verify:

```
Plus @@ VarDecomp22 // Simplify
```

$$\sigma_u^2 + \lambda_0^2 + 2 \sqrt{\frac{2}{\pi}} \sqrt{\sigma_Q^2} \lambda_0 \lambda_1 + \sigma_Q^2 \lambda_1^2$$

■ Exercise 9.2 (Madhavan, Richardson and Roomans, Source notebook: MultivariateMicrostructureModels)

The model is:

```
QRule = Q_t_ -> v_t + β Q_{t-1};
mRule = m_t_ -> m_{t-1} + w_t;
wRule = w_t_ -> λ v_t + u_t;
PRule = P_t_ -> m_t + c Q_t;
```

With these rules,  $q_t$ ,  $m_t$ ,  $w_t$ , and  $p_t$  are:

```
{q_t /. qRule, m_t /. mRule, w_t /. wRule, p_t /. pRule} // TableForm
```

```
β q_{-1+t} + v_t
m_{-1+t} + w_t
u_t + λ v_t
m_t + c q_t
```

The price change is  $\Delta p_t =$

```
ΔpRule = Δp_t_ -> Δp_t -> (p_t /. pRule /. mRule /. wRule) - (p_{t-1} /. pRule);
Simplify[Δp_t /. ΔpRule]
```

```
Δp_t -> -c q_{-1+t} + c q_t + u_t + λ v_t
```

The system variables are  $y_t =$

```
yRule = y_t_ -> Transpose[{{Δp_t, q_t}}]; y_t /. yRule // MatrixForm
```

```
( Δp_t
  q_t )
```

The vector of disturbances is:

```
εRule = ε_t_ -> Transpose[{{u_t, v_t}}]; ε_t /. εRule // MatrixForm
```

```
( u_t
  v_t )
```

```
ClearAll[θ]
```

With substitutions, the vector of system variables becomes  $y_t =$

```
{{Δp_t}, {q_t}} /. Δp_t -> (p_t /. pRule /. mRule /. wRule) - (p_{t-1} /. pRule) /. q_t -> (q_t /. qRule) //
Simplify // MatrixForm
```

```
( c (-1 + β) q_{-1+t} + u_t + (c + λ) v_t
  β q_{-1+t} + v_t )
```

This is a first-order vector autoregressive process:  $y_t = \phi y_{t-1} + \theta \epsilon_t$  where

```
φRule = φ -> {{0, c (-1 + β)}, {0, β}}; MatrixForm /@ φRule
```

```
φ -> ( 0 c (-1 + β)
       0 β )
```

and

```
 $\theta_{\text{Rule}} = \theta \rightarrow \{\{1, (c + \lambda)\}, \{0, 1\}\}; \text{MatrixForm} /@ \theta_{\text{Rule}}$ 
```

$$\theta \rightarrow \begin{pmatrix} 1 & c + \lambda \\ 0 & 1 \end{pmatrix}$$

It may be put in vector moving average (VMA) form as:  $y_t = \underbrace{(\mathbf{I} - \phi\mathbf{L})^{-1} \theta}_{\text{VMA coefficients}} \epsilon_t$ . We could obtain the VMA coefficient matrices by doing the series expansion. Here, though, to compute the random-walk variance, we just need the sum of the moving average coefficients, and  $(\mathbf{I} - \phi)^{-1} \theta =$

```
maSum = Inverse[IdentityMatrix[2] - (phi /. phiRule)].(theta /. thetaRule) // Simplify;
maSum // MatrixForm
```

$$\begin{pmatrix} 1 & \lambda \\ 0 & \frac{1}{1-\beta} \end{pmatrix}$$

To compute the random-walk variance  $\sigma_w^2$ , take the upper left hand entry of  $[(\mathbf{I} - \phi)^{-1} \theta] \Omega [(\mathbf{I} - \phi)^{-1} \theta]'$

```
maSum.{ {sigma_u^2, 0}, {0, sigma_v^2} }.Transpose[maSum] // Simplify // MatrixForm
```

$$\begin{pmatrix} \sigma_u^2 + \lambda^2 \sigma_v^2 & \frac{\lambda \sigma_v^2}{1-\beta} \\ \frac{\lambda \sigma_v^2}{1-\beta} & \frac{\sigma_v^2}{(-1+\beta)^2} \end{pmatrix}$$

The quantity  $\sigma_u^2 + \lambda^2 \sigma_v^2$  summarizes the public information and trade-related components of the random-walk.

### ■ Exercise 11.1 (Source notebook: DealersAndInventories)

(The numbers in Exercise 11.1 were used to generate the figure.)

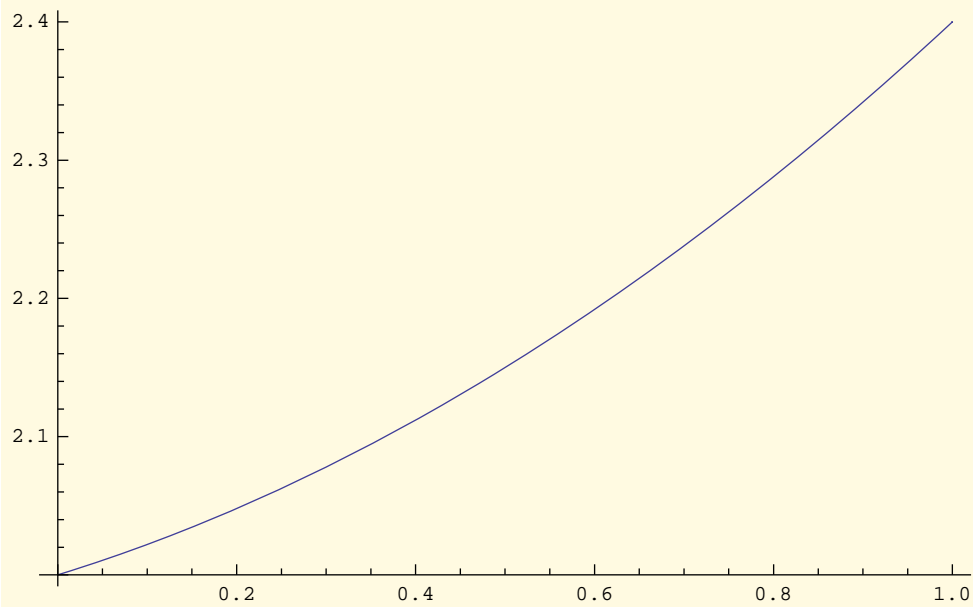
```
f[a_, b_, c_, x_] := a x^2 + b x + c;
```

Inverse arrival rates of sellers (who receive the bid price)

```
ps = f[.2, .2, 2, lambda]
```

$$2 + 0.2 \lambda + 0.2 \lambda^2$$

```
Plot[ps, {λ, 0, 1}]
```



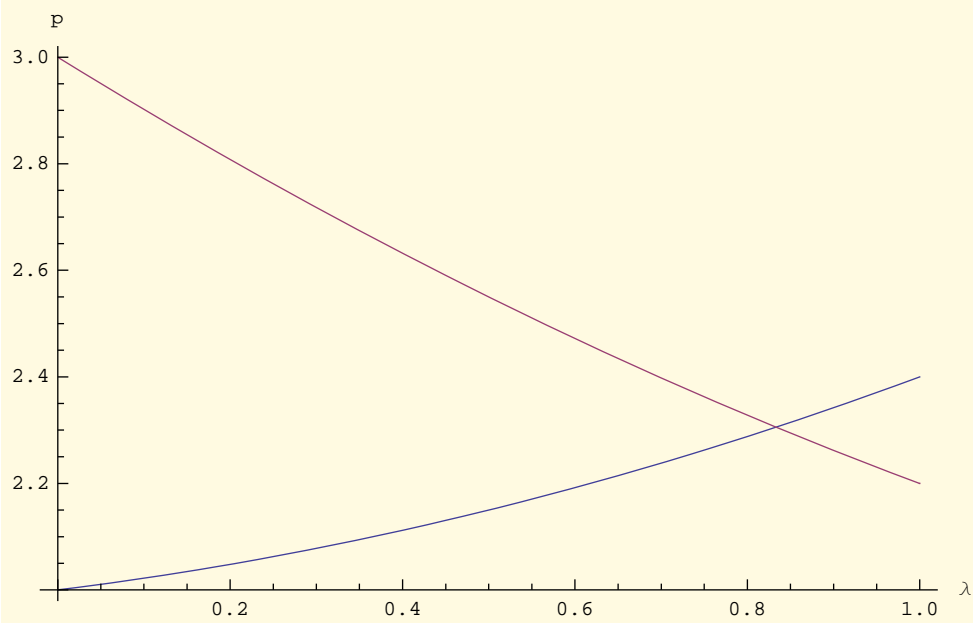
Inverse arrive rate of buyers (who pay the ask)

```
pb = f[.2, -1, 3, λ]
```

$$3 - \lambda + 0.2 \lambda^2$$

□ *The single price equilibrium*

```
Plot[{ps, pb}, {λ, 0, 1}, AxesLabel → {"λ", "p"}]
```





Determination of the single-price equilibrium arrival rate:

```
 $\lambda_{Eq} = \lambda /. Flatten[NSolve[ps == pb, \lambda]]$ 
```

```
0.833333
```

```
 $p_{Eq} = ps /. \lambda \rightarrow \lambda_{Eq}$ 
```

```
2.30556
```

(Optimal) average profit and arrival intensity:

```
 $sol = NMaximize[\{\lambda (pb - ps), \lambda > 0\}, \lambda]$ 
```

```
{0.208333, {\lambda \to 0.416667}}
```

```
 $\lambda_{Opt} = \lambda /. sol[[2, 1]]$ 
```

```
0.416667
```

```
 $bid = ps /. \lambda \rightarrow \lambda_{Opt}$ 
```

```
2.11806
```

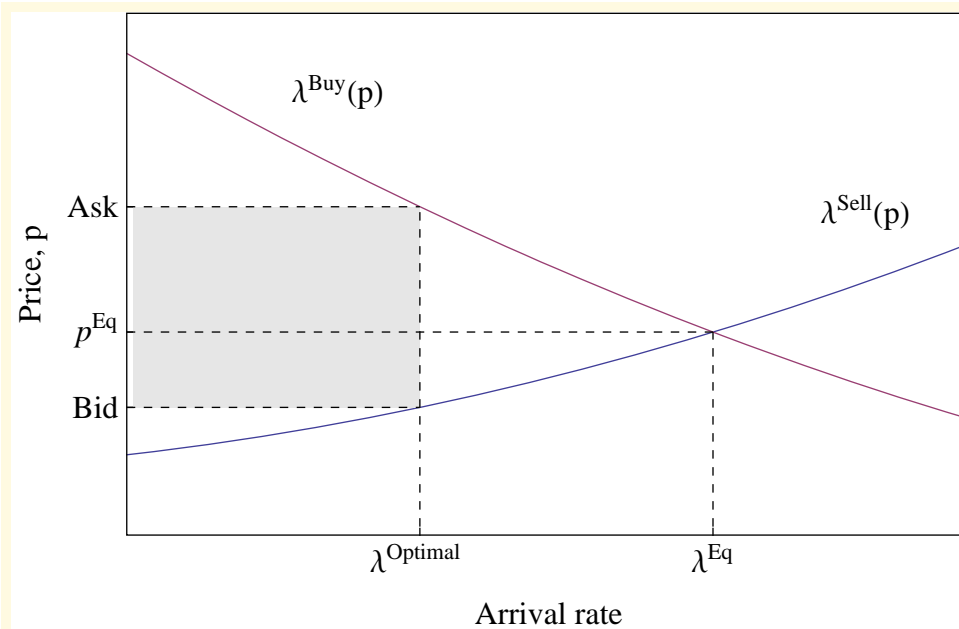
```
 $ask = pb /. \lambda \rightarrow \lambda_{Opt}$ 
```

```
2.61806
```

```

extra = {GrayLevel[0.9`], Rectangle[{0.01`, bid}, {λOpt, ask}],
  GrayLevel[0], Dashing[{0.01`}], Line[{{λOpt, 0}, {λOpt, ask}}],
  Line[{{0, bid}, {λOpt, bid}}], Line[{{0, ask}, {λOpt, ask}}],
  Line[{{λEq, 0}, {λEq, pEq}}], Line[{{0, pEq}, {λEq, pEq}}],
  Text["λBuy(p)", {0.3`, 2.9`}],
  Text["λSell(p)", {1.05`, 2.6`}]
};
Plot[{ps, pb}, {λ, 0, 1.2`}, PlotRange → {{0, 1.2`}, {1.8`, 3.1`}},
  Frame → True, FrameLabel → {"Arrival rate", "Price, p"},
  Background → GrayLevel[1], FrameTicks →
  {{{λOpt, "λOptimal"}, {λEq, "λEq"}, {bid, Bid}, {ask, Ask}, {pEq, "pEq"}}},
  None, None}, Epilog → extra, BaseStyle → baseStyle]

```



■ Exercise 15.1 (Source notebook: TradingStrategiesI)

□ Model dynamics

```

mRule = mt -> (mt-1 /. m0 -> 0) + λt st + μ + εt;
PRule = pt -> mt + γ (st /. s0 -> 0);
WRule = Wt -> Wt-1 - (st-1 /. s0 -> 0) /; ! t == 0;
εZap = ε- -> 0;

```

```
solution = OptOrders[3, {pRule, mRule, eZap} /.  $\mu \rightarrow 0$  /.  $\gamma \rightarrow 0$ ] // Simplify;
```

Lagrangian:  $\delta (1 - s_1 - s_2 - s_3) + s_1^2 \lambda_1 + s_2 (s_1 \lambda_1 + s_2 \lambda_2) + s_3 (s_1 \lambda_1 + s_2 \lambda_2 + s_3 \lambda_3)$

First order conditions:

$$-\delta + 2 s_1 \lambda_1 + s_2 \lambda_1 + s_3 \lambda_1 = 0$$

$$-\delta + s_1 \lambda_1 + 2 s_2 \lambda_2 + s_3 \lambda_2 = 0$$

$$-\delta + s_1 \lambda_1 + s_2 \lambda_2 + 2 s_3 \lambda_3 = 0$$

$$1 - s_1 - s_2 - s_3 = 0$$

Solutions:

$$\delta \rightarrow \frac{2 \lambda_1 (\lambda_2^2 + \lambda_1 \lambda_3 - 4 \lambda_2 \lambda_3)}{\lambda_2 (\lambda_2 - 4 \lambda_3)}$$

$$s_1 \rightarrow 1 + \frac{2 \lambda_1 \lambda_3}{\lambda_2^2 - 4 \lambda_2 \lambda_3}$$

$$s_2 \rightarrow \frac{\lambda_1 (\lambda_2 - 2 \lambda_3)}{\lambda_2 (\lambda_2 - 4 \lambda_3)}$$

$$s_3 \rightarrow -\frac{\lambda_1}{\lambda_2 - 4 \lambda_3}$$

```
solution /. { $\lambda_1 \rightarrow 2$ ,  $\lambda_2 \rightarrow 1$ ,  $\lambda_3 \rightarrow 1/2$ } // TableForm
```

$$\delta \rightarrow 0$$

$$s_1 \rightarrow -1$$

$$s_2 \rightarrow 0$$

$$s_3 \rightarrow 2$$

As a check, verify that with constant  $\lambda$ , we obtain the original solution to the basic problem.

```
solution /. { $\lambda_ \rightarrow \lambda$ } // TableForm
```

$$\delta \rightarrow \frac{4 \lambda}{3}$$

$$s_1 \rightarrow \frac{1}{3}$$

$$s_2 \rightarrow \frac{1}{3}$$

$$s_3 \rightarrow \frac{1}{3}$$