Econometrics I

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Econometrics I

Part 24 – Bayesian Estimation

Bayesian Estimators

"Random Parameters" vs. Randomly Distributed Parameters

Models of Individual Heterogeneity

- Random Effects: Consumer Brand Choice
- Fixed Effects: Hospital Costs

Bayesian Estimation

- Specification of conditional likelihood: f(data | parameters)
- Specification of priors: g(parameters)
- Posterior density of parameters:

 $f(\text{parameters}|\text{data}) = \frac{f(\text{data} | \text{parameters})g(\text{parameters})}{f(\text{data})}$

Posterior mean = E[parameters|data]

The Marginal Density for the Data is Irrelevant

 $f(\beta \mid data) = \frac{f(data \mid \beta)p(\beta)}{f(data)} = \frac{L(data \mid \beta)p(\beta)}{f(data)}$ Joint density of β and data is f(data, β) = L(data | β)p(β) Marginal density of the data is $f(data) = \int_{\beta} f(data,\beta) d\beta = \int_{\beta} L(data \mid \beta) p(\beta) d\beta$ Thus, $f(\beta \mid data) = \frac{L(data \mid \beta)p(\beta)}{\int_{\Omega} L(data \mid \beta)p(\beta)d\beta}$ Posterior Mean = $\int_{\beta} p(\beta | data) d\beta = \frac{\int_{\beta} \beta L(data | \beta)p(\beta) d\beta}{\int_{\beta} L(data | \beta)p(\beta) d\beta}$ Requires specification of the likelhood and the prior.

Computing Bayesian Estimators

First generation: Do the integration (math)

$$E(\beta | \text{data}) = \int_{\beta} \beta \frac{f(\text{data} | \beta)g(\beta)}{f(\text{data})} d\beta$$

Contemporary - Simulation:

- (1) Deduce the posterior
- (2) Draw random samples of draws from the posterior and compute the sample means and variances of the samples. (Relies on the law of large numbers.)

Modeling Issues

- As n →∞, the likelihood dominates and the prior disappears → Bayesian and Classical MLE converge. (Needs the mode of the posterior to converge to the mean.)
- Priors
 - Diffuse → large variances imply little prior information. (NONINFORMATIVE)
 - INFORMATIVE priors finite variances that appear in the posterior. "Taints" any final results.

A Practical Problem

Sampling from the joint posterior may be impossible. E.g., linear regression.

$$\begin{split} &f(\boldsymbol{\beta}, \sigma^2 \mid \boldsymbol{y}, \boldsymbol{X}) \propto \frac{[vs^2]^{v+2}}{\Gamma(v+2)} \left[\frac{1}{\sigma^2} \right]^{v+1} e^{-vs^2(1/\sigma^2)} [2\pi]^{-K/2} \mid \sigma^2(\boldsymbol{X}'\boldsymbol{X})^{-1} \mid^{-1/2} \\ &\times \exp(-(1/2)(\boldsymbol{\beta} - \boldsymbol{b})' [\sigma^2(\boldsymbol{X}'\boldsymbol{X})^{-1}]^{-1} (\boldsymbol{\beta} - \boldsymbol{b})) \\ &\text{What is this???} \\ &\text{To do 'simulation based estimation' here, we need joint} \\ &\text{observations on } (\boldsymbol{\beta}, \sigma^2). \end{split}$$

A Solution to the Sampling Problem

The joint posterior, $p(\beta, \sigma^2 | data)$ is intractable. But, For inference about β , a sample from the marginal posterior, $p(\beta | data)$ would suffice.

For inference about σ^2 , a sample from the marginal posterior of σ^2 , p(σ^2 |data) would suffice.

Can we deduce these? For this problem, we do have conditionals: $p(\boldsymbol{\beta}|\sigma^2, data) = N[\boldsymbol{b}, \sigma^2(\boldsymbol{X'X})^{-1}]$

$$p(\sigma^2 | \boldsymbol{\beta}, data) = K \times \frac{\Sigma_i (\boldsymbol{\gamma}_i - \boldsymbol{x}'_i \boldsymbol{\beta})^2}{\sigma^2} = a \text{ gamma distribution}$$

Can we use this information to sample from $p(\boldsymbol{\beta}|data)$ and $p(\sigma^2|data)$?

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The Gibbs Sampler

- **D** Target: Sample from marginals of $f(x_1, x_2) = joint distribution$
- Joint distribution is unknown or it is not possible to sample from the joint distribution.
- Assumed: $f(x_1|x_2)$ and $f(x_2|x_1)$ both known and samples can be drawn from both.
- Gibbs sampling: Obtain one draw from x_1, x_2 by many cycles between $x_1|x_2$ and $x_2|x_1$.
 - Start $x_{1,0}$ anywhere in the right range.
 - Draw $x_{2,0}$ from $x_2|x_{1,0}$.
 - Return to $x_{1,1}$ from $x_1|x_{2,0}$ and so on.
 - Several thousand cycles produces the draws
 - Discard the first several thousand to avoid initial conditions. (Burn in)
- Average the draws to estimate the marginal means.

Bivariate Normal Sampling

Draw a random sample from bivariate normal $\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix}$ (1) Direct approach: $\begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \Gamma \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$ where $\begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$ are two independent standard normal draws (easy) and $\Gamma = \begin{pmatrix} 1 & 0 \\ \theta_1 & \theta_2 \end{pmatrix}$ such that $\Gamma\Gamma' = \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix}$. $\theta_1 = \rho, \ \theta_2 = \sqrt{1 - \rho^2}$. (2) Gibbs sampler: $\mathbf{v}_1 \mid \mathbf{v}_2 \sim \mathbf{N} \left[\rho \mathbf{v}_2, \sqrt{1 - \rho^2} \right]$ $\mathbf{V}_2 \mid \mathbf{V}_1 \sim \mathbf{N} \left[\rho \mathbf{V}_1, \sqrt{1 - \rho^2} \right]$

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Gibbs Sampling for the Linear Regression Model

$$p(\boldsymbol{\beta}|\sigma^{2},\text{data}) = N[\boldsymbol{b},\sigma^{2}(\boldsymbol{X}'\boldsymbol{X})^{-1}]$$
$$p(\sigma^{2}|\boldsymbol{\beta},\text{data}) = K \times \frac{\sum_{i}(\boldsymbol{y}_{i} - \boldsymbol{x}_{i}'\boldsymbol{\beta})^{2}}{\sigma^{2}}$$

= a gamma distribution

Iterate back and forth between these two distributions

Application – the Probit Model

(a) $y_i^* = \mathbf{x}_i' \mathbf{\beta} + \varepsilon_i \qquad \varepsilon_i \sim N[0,1]$ (b) $y_i = 1$ if $y_i * > 0$, 0 otherwise Consider estimation of β and y^{*} (data augmentation) (1) If y^* were observed, this would be a linear regression $(y_i \text{ would not be useful since it is just sgn}(y_i^*).)$ We saw in the linear model before, $p(\beta | y_i^*, y_i)$ (2) If (only) β were observed, y^{*} would be a draw from the normal distribution with mean $\mathbf{x}_{i}^{\prime}\mathbf{\beta}$ and variance 1. But, y_i gives the sign of y_i * y_i * y_i * β_i , y_i is a draw from the truncated normal (above if y=0, below if y=1)

Gibbs Sampling for the Probit Model

- (1) Choose an initial value for β (maybe the MLE)
- (2) Generate y_i^* by sampling N observations from the truncated normal with mean $\mathbf{x}'_i \mathbf{\beta}$ and variance 1, truncated above 0 if $y_i = 0$, from below if $y_i = 1$.
- (3) Generate β by drawing a random normal vector with mean vector (X'X)⁻¹X'y * and variance matrix (X'X)⁻¹
- (4) Return to 2 10,000 times, retaining the last 5,000 draws first 5,000 are the 'burn in.'
- (5) Estimate the posterior mean of β by averaging the last 5,000 draws.

(This corresponds to a uniform prior over β .)

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Generating Random Draws from f(X)

The inverse probability method of sampling random draws:

If F(x) is the CDF of random variable x, then

a random draw on x may be obtained as $F^{-1}(u)$ where u is a draw from the standard uniform (0,1). Examples:

Exponential: $f(x)=\theta exp(-\theta x)$; $F(x)=1-exp(-\theta x)$ $x = -(1/\theta)log(1-u)$ Normal: $F(x) = \Phi(x)$; $x = \Phi^{-1}(u)$ Truncated Normal: $x=\mu_i + \Phi^{-1}[1-(1-u)^*\Phi(\mu_i)]$ for y=1; $x = \mu_i + \Phi^{-1}[u\Phi(-\mu_i)]$ for y=0.

```
? Generate raw data
Calc ; Ran(13579) $
Sample ; 1 - 250 $
Create ; x1 = rnn(0,1) ; x2 = rnn(0,1) $
Create ; ys = .2 + .5*x1 - .5*x2 + rnn(0,1) ; y = ys > 0 $
Namelist; x = one,x1,x2$
Matrix ; xxi = \langle x'x \rangle \$
Calc ; Rep = 200 ; Ri = 1/(\text{Rep}-25)$
? Starting values and accumulate mean and variance matrices
Matrix ; beta=[0/0/0] ; bbar=init(3,1,0);bv=init(3,3,0)$$
       = gibbs $ Markov Chain - Monte Carlo iterations
Proc
Do for ; simulate ; r =1, Rep $
? ------ [ Sample y* | beta ] ------
Create ; mui = x'beta ; f = rnu(0,1)
       ; if (y=1) ysg = mui + inp(1-(1-f)*phi(mui));
            (else) ysg = mui + inp( f *phi(-mui)) $
? ------ [ Sample beta | y*] ------
Matrix ; mb = xxi*x'ysq ; beta = rndm(mb,xxi) $
? ----- [ Sum posterior mean and variance. Discard burn in. ]
Matrix ; if[r > 25] ; bbar=bbar+beta ; bv=bv+beta*beta'$
Enddo ; simulate $
Endproc $
Execute ; Proc = Gibbs $
Matrix ; bbar=ri*bbar ; bv=ri*bv-bbar*bbar' $
Probit ; lhs = y ; rhs = x $
Matrix ; Stat(bbar, bv, x) $
```

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Example: Probit MLE vs. Gibbs

> Matrix	; Stat(bbar,bv)	; Stat(b,varb)	\$	-+
Number of	observations in	= 1000	-+	
Number of parameters computed here			= 3	1
Number of	degrees of freed	= 997	I	
+				-+
+	++-		+	++
Variable	Coefficient	Standard Error	b/St.Er.	P[Z >z]
BBAR_1	.21483281	.05076663	4.232	.0000
BBAR 2	.40815611	.04779292	8.540	.0000
BBAR 3	49692480	.04508507	-11.022	.0000
+	++-		+	++
Variable	Coefficient	Standard Error	b/St.Er.	P[Z >z]
+ В_1	.22696546	.04276520	5.307	.0000
в 2	.40038880	.04671773	8.570	.0000
в 3	50012787	.04705345	-10.629	.0000

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A Random Effects Approach

- Allenby and Rossi, "Marketing Models of Consumer Heterogeneity"
 - Discrete Choice Model Brand Choice
 - "Hierarchical Bayes"
 - Multinomial Probit

Panel Data: Purchases of 4 brands of Ketchup

Structure

Conditional data generation mechanism

 $y_{it,j} *= \mathbf{\beta}_{i} \mathbf{x}_{it,j} + \varepsilon_{it,j}, \text{ Utility for consumer } i, \text{ choice } t, \text{ brand } j.$ $Y_{it,j} = \mathbf{1}[y_{it,j} *= maximum \text{ utility among the } J \text{ choices}]$ $\mathbf{x}_{it,j} = (\text{constant, log price, "availability," "featured"})$ $\varepsilon_{it,j} \sim N[0, \lambda_{j}], \lambda_{1} = 1$

Implies a J outcome multinomial probit model.

Bayesian Priors

Prior Densities

 $\boldsymbol{\beta}_i \sim N[\overline{\boldsymbol{\beta}}, \mathbf{V}_{\beta}],$

Implies $\boldsymbol{\beta}_i = \overline{\boldsymbol{\beta}} + \mathbf{w}_i, \mathbf{w}_i \sim N[\mathbf{0}, \mathbf{V}_{\beta}]$

 $\lambda_j \sim Inverse \ Gamma[v, s_j]$ (looks like chi-squared), v=3, $s_i = 1$ Priors over model parameters

$$\overline{\beta} \sim N[\overline{\overline{\beta}}, a\mathbf{V}_{\beta}], \ \overline{\overline{\beta}} = \mathbf{0}$$
$$\mathbf{V}_{\beta}^{-1} \sim Wishart[v_0, \mathbf{V}_0], v_0 = 8, \mathbf{V}_0 = 8\mathbf{I}$$

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Bayesian Estimator

- □ Joint Posterior= $E[\beta_1, ..., \beta_N, \overline{\beta}, V_\beta, \lambda_1, ..., \lambda_J | data]$ □ Integral does not exist in closed form.
- Estimate by random samples from the joint posterior.
- Full joint posterior is not known, so not possible to sample from the joint posterior.

Gibbs Cycles for the MNP Model

Samples from the marginal posteriors Marginal posterior for the individual parameters (Known and can be sampled) $\boldsymbol{\beta}_i | \boldsymbol{\overline{\beta}}, \mathbf{V}_{\beta}, \boldsymbol{\lambda}, data$ Marginal posterior for the common parameters (Each known and each can be sampled) $\boldsymbol{\beta} | \mathbf{V}_{\beta}, \boldsymbol{\lambda}, data$ $\mathbf{V}_{\beta} | \overline{\boldsymbol{\beta}}, \boldsymbol{\lambda}, data$ $\lambda | \overline{\beta}, \mathbf{V}_{\beta}, , data$

Results

- Individual parameter vectors and disturbance variances
- Individual estimates of choice probabilities
- The same as the "random parameters model" with slightly different weights.
- Allenby and Rossi call the classical method an "approximate Bayesian" approach.
 - (Greene calls the Bayesian estimator an "approximate random parameters model")
 - Who's right?
 - Bayesian layers on implausible uninformative priors and calls the maximum likelihood results "exact" Bayesian estimators
 - Classical is strongly parametric and a slave to the distributional assumptions.
 - Bayesian is even more strongly parametric than classical.
 - Neither is right Both are right.

Comparison of Maximum Simulated Likelihood and Hierarchical Bayes

- Ken Train: "A Comparison of Hierarchical Bayes and Maximum Simulated Likelihood for Mixed Logit"
- Mixed Logit

$$U(i,t,j) = \beta'_{i} \mathbf{x}(i,t,j) + \varepsilon(i,t,j),$$

$$i = 1,..., N \text{ individuals,}$$

$$t = 1,..., T_{i} \text{ choice situations}$$

$$j = 1,..., J \text{ alternatives (may also vary)}$$

Stochastic Structure – Conditional Likelihood

$$Pr ob(i, j, t) = \frac{exp(\boldsymbol{\beta}'_{i} \mathbf{x}_{i, j, t})}{\sum_{j=1}^{J} exp(\boldsymbol{\beta}'_{i} \mathbf{x}_{i, j, t})}$$
$$Likelihood = \prod_{t=1}^{T} \frac{exp(\boldsymbol{\beta}'_{i} \mathbf{x}_{i, j^{*}, t})}{\sum_{j=1}^{J} exp(\boldsymbol{\beta}'_{i} \mathbf{x}_{i, j^{*}, t})}$$

 j^* = indicator for the specific choice made by i at time t.

Note individual specific parameter vector, β_i

Classical Approach

$$\beta_{i} \sim N[\mathbf{b}, \Omega]; \text{ write } \Omega = \Gamma \Gamma'$$

$$\beta_{i} = \mathbf{b} + \mathbf{w}_{i}$$

$$= \mathbf{b} + \Gamma \mathbf{v}_{i} \text{ where } \Gamma = diag(\gamma_{j}^{1/2}) \text{ (uncorrelated)}$$

$$Log - likelihood = \sum_{i=1}^{N} \log \int_{\mathbf{w}} \prod_{t=1}^{T} \frac{\exp[(\mathbf{b} + \mathbf{w}_{i})'\mathbf{x}_{i,j*,t}]}{\sum_{j=1}^{J} \exp[(\mathbf{b} + \mathbf{w}_{i})'_{i}\mathbf{x}_{i,j,t}]} d\mathbf{w}_{i}$$

Maximize over \mathbf{b}, Γ using maximum simulated likelihood

(random parameters model)

Bayesian Approach – Gibbs Sampling and Metropolis-Hastings

$$\begin{aligned} Posterior &= \prod_{i=1}^{N} L(data \mid \beta_{i}, \mathbf{\Omega}) \times priors \\ Prior &= N(\beta_{1}, ..., \beta_{N} \mid \mathbf{b}, \mathbf{\Omega}) \ (normal) \\ &\times IG(\gamma_{1}, ..., \gamma_{N} \mid parameters) \ (Inverse \ gamma) \\ &\times g(\mathbf{b} \mid assumed \ parameters) \ (Normal \ with \ large \ variance) \end{aligned}$$

Gibbs Sampling from Posteriors: **b**

$$p(\mathbf{b} | \beta_1, ..., \beta_N, \Omega) = Normal[\overline{\beta}, (1/N)\Omega]$$
$$\overline{\beta} = (1/N) \sum_{i=1}^N \beta_i$$

Easy to sample from Normal with known mean and variance by transforming a set of draws from standard normal.

Gibbs Sampling from Posteriors: Ω

 $p(\gamma_k | \mathbf{b}, \beta_1, ..., \beta_N) \sim Inverse \ Gamma[1+N, 1+NV_k]$ $\overline{V}_{k} = (1/N) \sum_{i=1}^{N} (\beta_{k,i} - b_{k})^{2}$ for each k=1,...,K Draw from inverse gamma for each k: Draw 1+N draws from $N[0,1] = h_{r,k}$,

then the draw is $\frac{(1+NV_k)}{\sum_{k=1}^{R}h_{rk}^2}$

Part 24: Bayesian Estimation

Gibbs Sampling from Posteriors: β_i

 $p(\beta_i | \mathbf{b}, \mathbf{\Omega}) = M \times L(data | \beta_i) \times g(\beta_i | \mathbf{b}, \mathbf{\Omega})$ M=a constant, L=likelihood, g=prior (This is the definition of the posterior.) Not clear how to sample. Use Metropolis Hastings algorithm.

Metropolis – Hastings Method

Define : $\beta_{i,0} = an \text{ 'old' draw (vector)}$ $\beta_{i,1} = the \text{ 'new' draw (vector)}$ $d_r = \sigma \Gamma v_r,$

 σ =a constant (see below)

 Γ = the diagonal matrix of standard deviations \mathbf{v}_r = a vector of K draws from standard normal

Metropolis Hastings: A Draw of β_i

Trial value:
$$\tilde{\beta}_{i,1} = \beta_{i,0} + d_r$$

$$R = \frac{Posterior(\tilde{\beta}_{i,1})}{Posterior(\beta_{i,0})} (Ms \ cancel)$$

U = a random draw from U(0,1) If U < R, use $\tilde{\beta}_{i,1}$, *else keep* $\beta_{i,0}$ During Gibbs iterations, draw $\beta_{i,1}$ σ controls acceptance rate. Try for .4.

Application: Energy Suppliers

N=361 individuals, 2 to 12 hypothetical suppliers

- \square X= (1) fixed rates,
 - (2) contract length,
 - (3) local (0,1),
 - (4) well known company (0,1),
 - (5) offer TOD rates (0,1),
 - (6) offer seasonal rates (0,1).

Estimates: Mean of Individual β_i

	MSL Estimate	Bayes Posterior Mean
Price	-1.04 (0.396)	-1.04 (0.0374)
Contract	-0.208 (0.0240)	-0.194 (0.0224)
Local	2.40 (0.127)	2.41 (0.140)
Well Known	1.74 (0.0927)	1.71 (0.100)
TOD	-9.94 (0.337)	-10.0 (0.315)
Seasonal	-10.2 (0.333)	-10.2 (0.310)

Reconciliation: A Theorem (Bernstein-Von Mises)

- The posterior distribution converges to normal with covariance matrix equal to 1/n times the information matrix (same as classical MLE). (The distribution that is converging is the posterior, not the sampling distribution of the estimator of the posterior mean.)
- The posterior mean (empirical) converges to the mode of the likelihood function. Same as the MLE. A proper prior disappears asymptotically.
- Asymptotic sampling distribution of the posterior mean is the same as that of the MLE.